



Optimal error estimate of the finite element approximation of second order semilinear non-autonomous parabolic PDEs

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Abstract

In this work, numerical approximation of the second order non-autonomous semilinear parabolic partial differential equations (PDEs) is investigated using the classical finite element method. To the best of our knowledge, only the linear case is investigated in the literature. Using an approach based on evolution operator depending on two parameters, we obtain the error estimate of the semi-discrete scheme based on finite element method toward the mild solution of semilinear non-autonomous PDEs under polynomial growth and one-sided Lipschitz conditions of the nonlinear term. Our convergence rate is obtained with general non-smooth initial data, and is similar to that of the autonomous case. Such convergence result is very important in numerical analysis. For instance, it is one step forward for numerical approximation of non-autonomous stochastic partial differential equations with the finite element method.

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1. Introduction

Nonlinear partial differential equations are powerful tools in modelling real-world phenomena in many fields such as in geo-engineering. For instance oil and gas recovery from hydrocarbon reservoirs and mining heat from geothermal reservoirs can be modelled by nonlinear equations with possibly degeneracy appearing in the diffusion and transport terms. Since explicit solutions of many PDEs are rarely known, numerical approximations are powerful tools to provide realistic approximations. Approximations are usually done at two levels, namely space and time approximations. Only time approximations received so far some attentions (see for example [9] and reference therein), while the space approximation has been lacked. Our goal is to fill that gap by focusing on spatial approximation of the following advection–diffusion equation with a nonlinear reaction term using the finite element method

$$\frac{\partial u}{\partial t} = \mathcal{A}(t)u + F(t, u), \quad u(0) = u_0, \quad t \in (0, T], \quad T > 0. \tag{1}$$

The mild solution is sought in the Hilbert space $H = L^2(\Lambda)$, where Λ is assumed to have smooth boundary or is a convex polygon of \mathbb{R}^d ($d = 1, 2, 3$). The second order differential operator $\mathcal{A}(t)$ is given by

$$\mathcal{A}(t)u = \sum_{i,j=1}^d \frac{\partial}{\partial x_i} \left(q_{i,j}(t, x) \frac{\partial u}{\partial x_j} \right) - \sum_{j=1}^d q_j(t, x) \frac{\partial u}{\partial x_j} + q_0(t, x)u, \tag{2}$$

where $q_{i,j}, q_j$ and q_0 are smooth coefficients on the spatial variable, i.e. $q_{i,j}, q_j, q_0 \in C^1(\Lambda)$, $i, j = 1, \dots, d$. We also assume $q_{i,j}, q_j, q_0$ to be time differentiable (i.e. for all $x \in \Lambda$ $q_{i,j}(\cdot, x), q_j(\cdot, x), q_0(\cdot, x) \in C^1((0, T), \mathbb{R})$) and there exist $c_1 \geq 0, 0 < \gamma \leq 1$ such that

$$|q_{i,j}(t, x) - q_{i,j}(s, x)| \leq c_1 |t - s|^\gamma, \quad x \in \Lambda, \quad t, s \in [0, T], \quad i, j \in \{1, \dots, d\}.$$

Moreover, $q_{i,j}$ is assumed to satisfy the following ellipticity condition

$$\sum_{i,j=1}^d q_{i,j}(t, x) \xi_i \xi_j \geq c |\xi|^2, \quad (t, x) \in [0, T] \times \bar{\Lambda}, \tag{3}$$

where $c > 0$ is a constant. The finite element approximation of (1) with constant linear operator $\mathcal{A}(t) = \mathcal{A}$ are widely investigated in the scientific literature, see example [1,4,8,13] and the references therein. The finite volume method for $\mathcal{A}(t) = \mathcal{A}$ was recently investigated in [11]. If we turn our attention to the non-autonomous case, the list of references becomes remarkably short. For the linear homogeneous case ($F(t, u) = 0$), the finite element approximation has been investigated in [6], [1, Chapter III, Section 14.2]. The linear inhomogeneous version of (1) ($F(t, u) = f(t)$) was investigated in [5–7], [1, Chapter III, Section 12] and the references therein. To the best of our knowledge, the nonlinear case is not yet investigated in the scientific literature. This paper fills that gap by investigating the error estimate of the finite element method of (1) with a nonlinear term $F(t, u)$. The challenge increases when the nonlinear function satisfies the polynomial growth and the one-sided Lipschitz conditions than satisfying the global Lipschitz condition, which is restrictive and excludes many problems such as Allen–Cahn equation, for which $F(u) = u - u^3$. Our strategy is based on the introduction of an auxiliary problem, namely (65) lying on two parameters evolution operator and exploits carefully its smooth regularity properties. Our key intermediate result in Lemma 3.1 generalizes [13, Theorem 3.5] to semilinear problems with time dependent and not necessary self-adjoint operators. Furthermore, it also generalizes [13, Theorem 4.2], the results

in [1, Chapter III, Section 12] and in [5–7] to smooth and non-smooth initial data. Note that [Lemma 3.1](#) for non-smooth initial data is of great importance in numerical analysis. Our result is very useful while studying the convergence of the finite element method for many nonlinear problems, including stochastic partial differential equations (SPDEs), see for example [2,3,14] and references therein for time independent SPDEs. In fact, in the case of SPDEs, due to the Itô-isometry or the Burkholder–Davis–Gundy inequality, the non-smooth version of [Lemma 3.1](#) cannot be applied since it brings degenerated integrals, which cause difficulties in the error estimates or reduce considerably the order of convergence. Hence, our result is more general than the existing results (even for linear problems) and has many applications. To sum up, our main contribution and main difficulties lie on

- Establishing [Lemma 3.1](#), which is our key ingredient. Such results for autonomous problems with self-adjoint linear operator were thoroughly investigated in [13], revealing the importance of such estimate in numerical analysis. Here, the non-autonomous and not necessarily self-adjoint version is investigated.
- Estimating the semi-discrete error for semilinear problem with nonglobal Lipschitz condition ([Theorem 3.2](#)), which is more challenging and includes more realistic problems such as Allen–Cahn equation.

The convergence rate achieved for semilinear problem is in agreement with many results in the literature for autonomous problems and for non-autonomous linear problems. More precisely, we achieve convergence order $\mathcal{O}(h^2 t^{-1+\beta/2} + h^2(1 + \ln(t/h^2)))$ or $\mathcal{O}(h^\beta)$, where β is a regularity parameter defined in [Assumption 2.1](#). Furthermore, under optimal regularity of the nonlinear function F or under a linear growth assumption on F , we achieve optimal convergence order $\mathcal{O}(h^2 t^{-1+\beta/2})$. Following [11] and using the similar approach based on the two parameters evolution operator, this work can be extended to the finite volume method. The rest of this paper is structured as follows. In [Section 2](#), the well-posedness result is provided along with the finite element approximation. The error estimate is analysed in [Section 3](#) for both global Lipschitz nonlinear term and polynomial growth nonlinear term.

2. Mathematical setting and numerical approximation

2.1. Notations, settings and well-posedness problem

We denote by $\|\cdot\|$ the norm associated to the inner product $\langle \cdot, \cdot \rangle_H$ in the Hilbert space $H = L^2(\Lambda)$. We denote by $\mathcal{L}(H)$ the set of bounded linear operators in H . Let $\mathcal{C} := \mathcal{C}(\bar{\Lambda}, \mathbb{R})$ be the set of continuous functions equipped with the norm $\|u\|_{\mathcal{C}} := \sup_{x \in \bar{\Lambda}} |u(x)|$, $u \in \mathcal{C}$. To ensure the well posedness of (1), we make the following assumptions.

Assumption 2.1. The initial data u_0 belongs to $\mathcal{D}\left((-A(0))^{\frac{\beta}{2}}\right)$, $0 \leq \beta \leq 2$.

Assumption 2.2. The nonlinear function $F : [0, T] \times H \rightarrow H$ is Lipschitz continuous, i.e. there exists a constant K such that

$$\|F(t, v) - F(s, w)\| \leq K(|t - s| + \|v - w\|), \quad s, t \in [0, T], \quad v, w \in H. \quad (4)$$

We introduce two spaces \mathbb{H} and V , such that $\mathbb{H} \subset V$, depending on the boundary conditions of $-\mathcal{A}(t)$. For Dirichlet boundary conditions, we take $V = \mathbb{H} = H_0^1(\Lambda)$. For Robin boundary condition, we take $V = H^1(\Lambda)$ and

$$\mathbb{H} = \{v \in H^2(\Lambda) : \partial v / \partial \nu_{\mathcal{A}} + \alpha_0 v = 0, \quad \text{on } \partial \Lambda\}, \quad \alpha_0 \in \mathbb{R}, \quad (5)$$

where $\partial v / \partial \nu_{\mathcal{A}}$ stands for the differentiation along the outer conormal vector $\nu_{\mathcal{A}}$. One can easily check (see [1, Chapter III, (11.14')]) that the bilinear operator $a(t)$, associated to $-\mathcal{A}(t)$ defined by $a(t)(u, v) = \langle -\mathcal{A}(t)u, v \rangle_H$, $u \in \mathcal{D}(\mathcal{A}(t))$, $v \in V$ satisfies

$$a(t)(v, v) \geq \lambda_0 \|v\|_1^2 - c_0 \|v\|^2, \quad v \in V. \tag{6}$$

with $\lambda_0 > 0$ and $c_0 \in \mathbb{R}$. By adding and subtracting $c_0 u$ on the right hand side of (1), we have a new linear operator that we still call $\mathcal{A}(t)$ corresponding to the new bilinear form that we still call $a(t)$ such that the following coercivity property holds

$$a(t)(v, v) \geq \lambda_0 \|v\|_1^2, \quad v \in V, \quad t \in [0, T], \tag{7}$$

where λ_0 is a positive constant, independent of t . Note that $a(t)(\cdot, \cdot)$ is bounded in $V \times V$ ([1, Chapter III, (11.13)]), so the following operator $A(t) : V \rightarrow V^*$ is well defined

$$a(t)(u, v) = \langle -A(t)u, v \rangle \quad u, v \in V, \quad t \in [0, T],$$

where V^* is the dual space of V and $\langle \cdot, \cdot \rangle$ the duality pairing between V^* and V . Identifying H to its adjoint space H^* , we have the following continuous and dense inclusions

$$V \subset H \subset V^*, \quad \text{and therefore} \quad \langle u, v \rangle_H = \langle u, v \rangle, \quad u \in H, \quad v \in V.$$

So if we want to replace $\langle \cdot, \cdot \rangle$ by the scalar product of $\langle \cdot, \cdot \rangle_H$ on H , we therefore need to have $A(t)u \in H$, for $u \in V$. So the domain of $-A(t)$ is defined as

$$D := \mathcal{D}(-A(t)) = \mathcal{D}(A(t)) = \{u \in V, A(t)u \in H\}.$$

It is well known (see [1, Chapter III, (11.11) & (11.11')]) that in the case of Dirichlet boundary conditions $D = H_0^1(\Lambda) \cap H^2(\Lambda)$ and in the case of Robin boundary conditions $D = \mathbb{H}$ in (5). We write the restriction of $A(t) : V \rightarrow V^*$ to $\mathcal{D}(A(t))$ again $A(t)$ which is therefore regarded as an operator of H (more precisely the H realization of $\mathcal{A}(t)$).

The coercivity property (7) implies that $-A(t)$ is a positive operator and its fractional powers are well defined [1,4]. The following equivalence of norms holds [1,4]

$$\|v\|_{H^\alpha(\Lambda)} \equiv \|((-A(t))^{\frac{\alpha}{2}}v)\| := \|v\|_\alpha, \quad v \in \mathcal{D}((-A(t))^{\frac{\alpha}{2}}) \cap H^\alpha(\Lambda), \quad \alpha \in [0, 2]. \tag{8}$$

It is well known that the family of operators $\{A(t)\}_{0 \leq t \leq T}$ generates a family of two parameters operators $\{U(t, s)\}_{0 \leq s \leq t \leq T}$ (see for example [10] or [1, Page 832]). The evolution equation (1) can be written as follows

$$\frac{du(t)}{dt} = A(t)u(t) + F(t, u(t)), \quad u(0) = u_0, \quad t \in (0, T]. \tag{9}$$

The following theorem provides the well-posedness of problem (1) (or (9)).

Theorem 2.1 ([10]). *Let Assumption 2.2 be fulfilled. If $u_0 \in H$, then the initial value problem (1) has a unique mild solution $u(t)$ given by*

$$u(t) = U(t, 0)u_0 + \int_0^t U(t, s)F(s, u(s))ds, \quad t \in (0, T]. \tag{10}$$

Moreover, if Assumption 2.1 is fulfilled, then the following space regularity holds¹

$$\|(-A(s))^{\frac{\beta}{2}}u(t)\| + \|F(u(t))\| \leq C \left(1 + \|(-A(s))^{\frac{\beta}{2}}u_0\|\right), \quad \beta \in [0, 2), \quad s, t \in [0, T]. \tag{11}$$

¹ This estimate also holds when u is replaced by its semi-discrete version u^h defined in Section 2.2.

2.2. Finite element discretization

Let \mathcal{T}_h be a triangulation of Λ with maximal length h . Let $V_h \subset V$ denote the space of continuous and piecewise linear functions over the triangulation \mathcal{T}_h . We define the projection P_h from $H = L^2(\Lambda)$ to V_h by

$$\langle P_h u, \chi \rangle_H = \langle u, \chi \rangle_H, \quad \chi \in V_h, u \in H. \tag{12}$$

For any $t \in [0, T]$, the discrete operator $A_h(t) : V_h \rightarrow V_h$ is defined by

$$\langle A_h(t)\phi, \chi \rangle_H = -\langle (-A(t))^{1/2}\phi, (-A(t))^{*1/2}\chi \rangle_H = -a(t)(\phi, \chi), \quad \phi, \chi \in V_h. \tag{13}$$

Note that $(-A(t))^{*1/2}$ stands for the adjoint of $(-A(t))^{1/2}$.

The space semi-discrete version of problem (9) consists of finding $u^h(t) \in V_h$ such that

$$\frac{du^h(t)}{dt} = A_h(t)u^h(t) + P_h F(t, u^h(t)), \quad u^h(0) = P_h u_0, \quad t \in (0, T]. \tag{14}$$

For $t \in [0, T]$, we introduce the Ritz projection $R_h(t) : V \rightarrow V_h$ defined by

$$\langle -A(t)R_h(t)v, \chi \rangle_H = a(t)(v, \chi), \quad v \in V, \quad \chi \in V_h. \tag{15}$$

It is well known (see e.g. [6, (3.2)] or [1]) that the following error estimate holds

$$\|R_h(t)v - v\| + h\|R_h(t)v - v\|_{H^1(\Lambda)} \leq Ch^r \|v\|_{H^r(\Lambda)}, \quad v \in V \cap H^r(\Lambda), \quad r \in [1, 2]. \tag{16}$$

The following error estimate also holds (see for example [6, (3.3)] or [1])

$$\|D_t (R_h(t)v - v)\| + h\|D_t (R_h(t)v - v)\|_{H^1(\Lambda)} \leq Ch^r (\|v\|_{H^r(\Lambda)} + \|D_t v\|_{H^r(\Lambda)}), \tag{17}$$

for any $r \in [1, 2]$ and $v \in V \cap H^r(\Lambda)$, where $D_t := \frac{\partial}{\partial t}$ and $D_t R_h(t) = R'_h(t)$ is the time derivative of R_h . According to the generation theory, $A_h(t)$ generates a two parameters evolution operator $\{U_h(t, s)\}_{0 \leq s \leq t \leq T}$ (see for example [1, Page 839]). Therefore the mild solution of (14) can be written as follows

$$u^h(t) = U_h(t, 0)P_h u_0 + \int_0^t U_h(t, s)P_h F(s, u^h(s))ds, \quad t \in [0, T]. \tag{18}$$

In the rest of this paper, $C \geq 0$ stands for a constant independent of h , that may change from one place to another. It is well known (see example. [1, Chapter III, (12.3) & (12.4)]) that for any $0 \leq \gamma \leq \alpha \leq 1$ and $0 \leq s < t \leq T$, the following estimates hold²

$$\|(-A_h(t))^\alpha U_h(t, s)\|_{\mathcal{L}(H)} \leq C(t - s)^{-\alpha}, \quad \|U_h(t, s)(-A_h(s))^\alpha\|_{\mathcal{L}(H)} \leq C(t - s)^{-\alpha}. \tag{19}$$

3. Main result

3.1. Preliminaries result

We consider the following linear homogeneous problem: find $w \in D \subset V$ such that

$$w' = A(t)w, \quad w(\tau) = v, \quad t \in (\tau, T], \quad \text{with } 0 \leq \tau \leq T. \tag{20}$$

The corresponding semi-discrete problem in space is: find $w_h \in V_h$ such that

$$w'_h(t) = A_h(t)w_h, \quad w_h(\tau) = P_h v, \quad t \in (\tau, T], \quad \text{with } 0 \leq \tau \leq T. \tag{21}$$

The following lemma will be useful in our convergence analysis.

² These estimates remain true if $A_h(t)$ and $U_h(t, s)$ are replaced by $A(t)$ and $U(t, s)$ respectively.

Lemma 3.1. *Let $r \in [0, 2]$ and $\gamma \leq r$. Let Assumption 2.2 be fulfilled. Then the following error estimate holds for the semi-discrete approximation (21)*

$$\begin{aligned} \|w(t) - w_h(t)\| &= \|[U(t, \tau) - U_h(t, \tau)P_h]v\| \\ &\leq Ch^r(t - \tau)^{-\frac{(r-\gamma)}{2}} \|v\|_\gamma, \quad v \in \mathcal{D}\left((-A(0))^{\frac{\gamma}{2}}\right). \end{aligned}$$

Proof. We split the desired error as follows

$$w_h(t) - w(t) = (w_h(t) - R_h(t)w(t)) + (R_h(t)w(t) - w(t)) \equiv \theta(t) + \rho(t). \tag{22}$$

Using the definition of $R_h(t)$ and P_h ((12)–(13)), we can prove exactly as in [4] that

$$A_h(t)R_h(t) = P_hA(t), \quad t \in [0, T]. \tag{23}$$

One can easily compute the following derivatives

$$D_t\theta = A_h(t)w_h(t) - D_tR_h(t)w(t) - R_h(t)A(t)w(t), \tag{24}$$

$$D_t\rho = D_tR_h(t)w(t) + R_h(t)A(t)w(t) - A(t)w(t). \tag{25}$$

Endowing V and the linear subspace V_h with the norm $\|\cdot\|_{H^1(\Lambda)}$, it follows from (16) that $R_h(t) \in \mathcal{L}(V, V_h)$, $t \in [0, T]$. By the definition of the differential operator, it follows that $D_tR_h(t) \in \mathcal{L}(V, V_h)$ for all $t \in [0, T]$. Hence $P_hD_tR_h(t) = D_tR_h(t)$ for all $t \in [0, T]$ and it follows from (25) that

$$P_hD_t\rho = D_tR_h(t)w(t) + R_h(t)A(t)w(t) - P_hA(t)w(t). \tag{26}$$

Adding and subtracting $P_hA(t)w(t)$ in (24) and using (23), it follows that

$$D_t\theta = A_h(t)\theta - P_hD_t\rho, \quad t \in (\tau, T], \tag{27}$$

From (24), the mild solution of θ is given by

$$\theta(t) = U_h(t, \tau)\theta(\tau) - \int_\tau^t U_h(t, s)P_hD_s\rho(s)ds. \tag{28}$$

Splitting the integral part of (28) in two and integrating by parts the first one yields

$$\begin{aligned} \theta(t) &= U_h(t, \tau)\theta(\tau) + U_h(t, \tau)P_h\rho(\tau) - U_h(t, (t + \tau)/2)P_h\rho((t + \tau)/2) \\ &\quad + \int_\tau^{(t+\tau)/2} \frac{\partial}{\partial s}(U_h(t, s))P_h\rho(s)ds - \int_{(t+\tau)/2}^t U_h(t, s)P_hD_s\rho(s)ds. \end{aligned} \tag{29}$$

Using the expression of $\theta(\tau)$, $\rho(\tau)$ (see (22)) and the fact that $w_h(\tau) = P_hv$, it holds that $\theta(\tau) + P_h\rho(\tau) = 0$. Hence (29) reduces to

$$\begin{aligned} \theta(t) &= -U_h(t, s)P_h\rho((t + \tau)/2) + \int_\tau^{(t+\tau)/2} \frac{\partial}{\partial s}(U_h(t, s))P_h\rho(s)ds \\ &\quad - \int_{(t+\tau)/2}^t U_h(t, s)P_hD_s\rho(s)ds. \end{aligned} \tag{30}$$

Taking the norms on both sides of (30) and using (19) yields

$$\begin{aligned} \|\theta(t)\| &\leq C \|\rho((t + \tau)/2)\| + \int_\tau^{(t+\tau)/2} \|U_h(t, s)A_h(s)\|_{\mathcal{L}(H)} \|\rho(s)\|ds + \int_{(t+\tau)/2}^t \|D_s\rho(s)\|ds \\ &\leq C \|\rho((t + \tau)/2)\| + \int_\tau^{(t+\tau)/2} (t - s)^{-1} \|\rho(s)\|ds + \int_{(t+\tau)/2}^t \|D_s\rho(s)\|ds. \end{aligned} \tag{31}$$

Using (16) and (17), it holds that

$$\|\rho(s)\| \leq Ch^r \|w(s)\|_r, \quad \|D_s \rho(s)\| \leq Ch^r (\|w(s)\|_r + \|D_s w(s)\|_r). \tag{32}$$

Note that the solution of (20) can be represented as follows.

$$w(s) = U(s, \tau)v, \quad s \geq \tau. \tag{33}$$

Pre-multiplying both sides of (33) by $(-A(s))^{\frac{r}{2}}$ and using (19) yields

$$\begin{aligned} \left\| (-A(s))^{\frac{r}{2}} w(s) \right\| &\leq \left\| (-A(s))^{\frac{r}{2}} U(s, \tau) (-A(\tau))^{-\frac{\gamma}{2}} \right\|_{\mathcal{L}(H)} \left\| (-A(\tau))^{\frac{\gamma}{2}} v \right\| \\ &\leq C(s - \tau)^{-\frac{(r-\gamma)}{2}} \left\| (-A(\tau))^{\frac{\gamma}{2}} v \right\| \leq C(s - \tau)^{-\frac{(r-\gamma)}{2}} \|v\|_\gamma. \end{aligned} \tag{34}$$

Therefore it holds that

$$\|w(s)\|_r \leq C(s - \tau)^{-\frac{(r-\gamma)}{2}} \|v\|_\gamma, \quad 0 \leq \gamma \leq r \leq 2, \quad \tau < s. \tag{35}$$

Substituting (35) in (32) yields

$$\|\rho(s)\|_r \leq Ch^r (s - \tau)^{-\frac{(r-\gamma)}{2}} \|v\|_\gamma. \tag{36}$$

Taking the derivative with respect to s on both sides of (33) yields

$$D_s w(s) = -A(s)U(s, \tau)v. \tag{37}$$

As for (34), pre-multiplying both sides of (37) by $(-A(s))^{\frac{r}{2}}$ and using (19) yields

$$\|D_s w(s)\|_r \leq C(s - \tau)^{-1-\frac{(r-\gamma)}{2}} \|v\|_\gamma. \tag{38}$$

Substituting (35) and (38) in the second estimate of (32) yields

$$\begin{aligned} \|D_s \rho(s)\| &\leq Ch^r \left((s - \tau)^{-\frac{(r-\gamma)}{2}} \|v\|_\gamma + (s - \tau)^{-1-\frac{(r-\gamma)}{2}} \|v\|_\gamma \right) \\ &\leq Ch^r (s - \tau)^{-1-\frac{(r-\gamma)}{2}} \|v\|_\gamma. \end{aligned} \tag{39}$$

Substituting the first estimate of (32) and (39) in (31) and using (36) yields

$$\begin{aligned} \|\theta(t)\| &\leq Ch^r (t - \tau)^{-\frac{(r-\gamma)}{2}} \|v\|_\gamma + Ch^r \int_\tau^{\frac{t+\tau}{2}} (t - s)^{-1} (s - \tau)^{-\frac{(r-\gamma)}{2}} \|v\|_\gamma ds \\ &\quad + Ch^r \int_{\frac{t+\tau}{2}}^t (s - \tau)^{-1-\frac{(r-\gamma)}{2}} \|v\|_\gamma ds. \end{aligned} \tag{40}$$

Using the estimate

$$\int_\tau^{\frac{t+\tau}{2}} (t - s)^{-1} (s - \tau)^{-\frac{(r-\gamma)}{2}} ds + \int_{\frac{t+\tau}{2}}^t (s - \tau)^{-1-\frac{(r-\gamma)}{2}} ds \leq C(t - \tau)^{-\frac{(r-\gamma)}{2}},$$

it follows from (40) that

$$\|\theta(t)\| \leq Ch^r (t - \tau)^{-\frac{(r-\gamma)}{2}} \|v\|_\gamma. \tag{41}$$

Substituting (36) and (41) in (22) completes the proof of Lemma 3.1. ■

3.2. Error estimate of the semilinear problem under global lipschitz condition

Theorem 3.1. *Let Assumptions 2.1 and 2.2 be fulfilled. Let $u(t)$ and $u^h(t)$ be defined by (10) and (18) respectively. Then the following error estimate holds*

$$\|u(t) - u^h(t)\| \leq Ch^2 t^{-1+\beta/2} + Ch^2(1 + \ln(t/h^2)), \quad 0 < t \leq T. \tag{42}$$

In addition, if the nonlinear term F satisfies the linear growth condition $\|F(t, v)\| \leq C\|v\|$ or if there exists $\delta > 0$ small enough such that $\|(-A(s))^\delta F(t, v)\| \leq Ct + C\|(-A(s))^\delta v\|$, $s, t \in [0, T]$, $v \in H$, then the following optimal error estimate holds

$$\|u(t) - u^h(t)\| \leq Ch^2 t^{-1+\beta/2}, \quad 0 < t \leq T, \tag{43}$$

where β is defined in [Assumption 2.1](#).

Remark 3.1. Note that the hypothesis $\|F(t, v)\| \leq C\|v\|$ is not too restrictive. An example of class of nonlinearities for which such hypothesis is fulfilled is a class of functions satisfying $F(t, 0) = 0$, $t \in [0, T]$. Concrete examples are operators of the form $F(t, v) = f(t) \frac{v}{1+|v|}$, with $f : [0, T] \rightarrow \mathbb{R}$ continuous or bounded on $[0, T]$.

Remark 3.2. It is possible to obtain an error estimate without irregularities terms of the form $t^{-1+\beta/2}$. The drawback here is that the convergence rate will not be 2, but will depend on the regularity of the initial data. The proof follows the same lines as that of [Theorem 3.1](#) using [Lemma 3.1](#) and we have

$$\|u(t) - u^h(t)\| \leq Ch^\beta, \quad t \in [0, T].$$

Proof. of [Theorem 3.1](#). We start with the proof of (42). Subtracting (18) from (10), taking the norm on both sides and using the triangle inequality yields

$$\begin{aligned} \|u(t) - u^h(t)\| &\leq \|U(t, 0)u_0 - U_h(t, 0)P_h u_0\| \\ &\quad + \left\| \int_0^t [U(t, s)F(s, u(s)) - U_h(t, s)P_h F(s, u^h(s))] ds \right\| =: I_0 + I_1. \end{aligned} \tag{44}$$

Using [Lemma 3.1](#) with $r = 2$ and $\gamma = \beta$ yields

$$I_0 \leq Ch^2 t^{-1+\beta/2} \|u_0\|_\beta \leq Ch^2 t^{-1+\beta/2}. \tag{45}$$

Using [Assumption 2.2](#), (11) and (19) yields

$$\begin{aligned} I_1 &\leq \int_0^t \|U(t, s) [F(s, u(s)) - F(s, u^h(s))]\| ds \\ &\quad + \int_0^t \|[U(t, s) - U_h(t, s)P_h] F(s, u^h(s))\| ds \\ &\leq C \int_0^t \|u(s) - u^h(s)\| ds + C \int_0^t \|[U(t, s) - U_h(t, s)P_h] F(s, u^h(s))\| ds. \end{aligned} \tag{46}$$

If $0 \leq t \leq h^2$, then using (19), [Assumption 2.2](#) and (11) yields

$$\begin{aligned} I_1 &\leq C \int_0^t \|u(s) - u^h(s)\| ds + C \int_0^t \|U(t, s) - U_h(t, s)P_h\|_{\mathcal{L}(H)} ds \\ &\leq C \int_0^t \|u(s) - u^h(s)\| ds + C \int_0^t ds \leq C \int_0^t \|u(s) - u^h(s)\| ds \\ &\leq C \int_0^t \|u(s) - u^h(s)\| ds + C \int_0^{h^2} ds \leq Ch^2 + C \int_0^t \|u(s) - u^h(s)\| ds. \end{aligned}$$

If $0 < h^2 \leq t$, using [Lemma 3.1](#) (with $r = 2$ and $\gamma = 0$), and splitting the second integral in two parts yields

$$\begin{aligned}
 I_1 &\leq C \int_0^t \|u(s) - u^h(s)\| ds + Ch^2 \int_0^{t-h^2} (t-s)^{-1} ds + Ch^2 \int_{t-h^2}^t (t-s)^{-1} ds \\
 &\leq C \int_0^t \|u(s) - u^h(s)\| ds + Ch^2(1 + \ln(t/h^2)).
 \end{aligned}
 \tag{47}$$

Substituting [\(45\)](#) and [\(47\)](#) in [\(44\)](#), and applying Gronwall’s lemma proves [\(42\)](#). To prove [\(43\)](#), we only need to re-estimate the term $I_3 := \int_0^t \| [U(t, s) - U_h(t, s)P_h] F(s, u^h(s)) \| ds$. Note that under assumption $\|(-A(s))^\delta F(t, v)\| \leq Ct + C\|(-A(s))^\delta v\|$, using [Lemma 3.1](#) (with $r = 2$ and $\gamma = \delta$) and [\(11\)](#), following the same lines as above, we obtain easily that $I_3 \leq Ch^2$. Let us now estimate I_3 under the hypothesis $\|F(t, v)\| \leq C\|v\|$. Using [Assumption 2.2](#), [\(11\)](#), we the help of the mild solution [\(18\)](#), we have

$$\|F(t, u^h(t))\| \leq \|u^h(t)\| \leq C|t-s|^\epsilon s^{-\epsilon}, \quad \|F(s, u^h(s)) - F(t, u^h(t))\| \leq C|t-s|^\epsilon s^{-\epsilon},
 \tag{48}$$

for some $\epsilon \in (0, 1)$ and any $s, t \in [0, T]$. Using [Lemma 3.1](#) (with $r = 2$ and $\gamma = 0$), triangle inequality and [\(48\)](#) yields

$$\begin{aligned}
 I_1 &\leq Ch^2 \int_0^t (t-s)^{-1} \|F(s, u^h(s)) - F(t, u^h(t))\| ds \\
 &\quad + Ch^2 \int_0^t (t-s)^{-1} \|F(t, u^h(t))\| ds \\
 &\leq Ch^2 \int_0^t (t-s)^{-1+\epsilon} s^{-\epsilon} ds \leq Ch^2.
 \end{aligned}$$

Hence the new estimate of I_1 is given by

$$I_1 \leq Ch^2 + C \int_0^t \|u(s) - u^h(s)\| ds.
 \tag{49}$$

Substituting [\(45\)](#) and [\(49\)](#) in [\(44\)](#) and applying Gronwall’s lemma proves [\(43\)](#) and the proof of [Theorem 3.1](#) is completed. ■

3.3. Error estimate for the semilinear problem under polynomial growth and one-sided lipschitz conditions

In this section, we take $\beta \in (\frac{d}{2}, 2)$ and make the following assumptions on the nonlinearity.

Assumption 3.1. There exist four constants $L_0, L_1, c_1, c_2 \in [0, \infty)$ such that the nonlinear function F satisfies the following conditions

$$(F(s, w) - F(s, v), w - v)_H \leq L_0 \|w - v\|^2, \quad w, v \in H,
 \tag{50}$$

$$\|F(s, w)\| \leq L_1 + L_1 \|w\| (1 + \|w\|_C^{c_1}), \quad w \in H,
 \tag{51}$$

$$\|F(s, w) - F(s, v)\| \leq L_1 \|w - v\| (1 + \|u\|_C^{c_1} + \|v\|_C^{c_1}), \quad w, v \in H,
 \tag{52}$$

for any $s \in [0, T]$.

Let us recall the following Sobolev embedding theorem.

$$\mathcal{D}((-A(0))^\delta) \hookrightarrow C(\Lambda, \mathbb{R}), \quad \text{for } \delta > \frac{d}{2}, \quad d \in \{1, 2, 3\}. \tag{53}$$

It is a classical solution that under [Assumption 3.1](#), (9) has a unique mild solution u satisfying $u \in C([0, T], H)$ (see for example [10]).

Lemma 3.2. *The mild solution u of (9) satisfies the following space regularity estimates³*

$$\|(-A(0))^{\frac{\beta}{2}}u(t)\| \leq C, \quad \|u(t)\|_C \leq C, \quad t \in [0, T]. \tag{54}$$

Proof. Having the first estimate of (54), the Sobolev embedding (53) allows to have

$$\|u(t)\|_C \leq C \left\| (-A(0))^{\frac{\beta}{2}}u(t) \right\| \leq C, \quad \|u^h(t)\|_C \leq C \left\| (-A(0))^{\frac{\beta}{2}}u^h(t) \right\| \leq C, \quad t \in [0, T]. \tag{55}$$

Hence, it remains to prove the first estimate of (54). Note that u satisfies

$$\frac{d}{dt}u(t) - A(t)u(t) = F(t, u(t)), \quad u(0) = u_0, \quad t \in (0, T]. \tag{56}$$

Taking the inner product in (56), using [Assumption 3.1](#) and Cauchy–Schwartz’s inequality yields

$$\begin{aligned} \frac{1}{2} \frac{d}{ds} \|u(s)\|^2 - \langle A(s)u(s), u(s) \rangle_H &= \langle F(s, u(s)) - F(s, 0), u(s) \rangle_H + \langle F(s, 0), u(s) \rangle_H \\ &\leq C \|u(s)\|^2 + \frac{1}{2} \|u(s)\|^2 + \frac{1}{2} \|F(s, 0)\|^2. \end{aligned} \tag{57}$$

Using the coercivity estimate (7), it holds that

$$\begin{aligned} \lambda_0 \|u(s)\|_1^2 \leq a(s) \langle u(s), u(s) \rangle &= -\frac{1}{2} \frac{d}{ds} \|u(s)\|^2 + \frac{1}{2} \frac{d}{ds} \|u(s)\|^2 - \langle A(s)u(s), u(s) \rangle_H \\ &\leq -\frac{1}{2} \frac{d}{ds} \|u(s)\|^2 + C \|u(s)\|^2 + \frac{1}{2} \|F(s, 0)\|^2. \end{aligned} \tag{58}$$

Using Cauchy–Schwartz’s inequality, [12, Lemma 3.1] and (58), it holds that

$$\begin{aligned} |\langle A(s)u(s), u(s) \rangle_H| &= \left| \left\langle (-A(s))^{\frac{1}{2}}u(s), (-A^*(s))^{\frac{1}{2}}u(s) \right\rangle_H \right| \\ &\leq \frac{1}{2} \left\| (-A(s))^{\frac{1}{2}}u(s) \right\|^2 + \frac{1}{2} \left\| (-A^*(s))^{\frac{1}{2}}u(s) \right\|^2 \\ &\leq \frac{C}{2} \|u(s)\|_1^2 + \frac{1}{2} \left\| (-A^*(s))^{\frac{1}{2}}(-A(s))^{-\frac{1}{2}} \right\|_{\mathcal{L}(H)}^2 \left\| (-A(s))^{\frac{1}{2}}u(s) \right\|^2 \\ &\leq \frac{C}{2} \|u(s)\|_1^2 + \frac{C}{2} \left\| (-A(s))^{\frac{1}{2}}u(s) \right\|^2 \leq C \|u(s)\|_1^2 = \frac{C}{\lambda_0} \cdot \lambda_0 \|u(s)\|_1^2 \\ &\leq -\frac{C}{2\lambda_0} \frac{d}{ds} \|u(s)\|^2 + C \|u(s)\|^2 + C \|F(s, 0)\|^2. \end{aligned} \tag{59}$$

³ These estimates still hold if u is replaced by its discrete version u^h .

Note that from (57) we have

$$\begin{aligned} \frac{1}{2} \frac{d}{ds} \|u(s)\|^2 &\leq C \|u(s)\|^2 + \frac{1}{2} \|F(s, 0)\|^2 + \langle A(s)u(s), u(s) \rangle_H \\ &\leq C \|u(s)\|^2 + \frac{1}{2} \|F(s, 0)\|^2 + |\langle A(s)u(s), u(s) \rangle_H|. \end{aligned} \tag{60}$$

Substituting (59) in (60) yields

$$\left(\frac{1}{2} + \frac{C}{2\lambda_0}\right) \frac{d}{ds} \|u(s)\|^2 \leq C \|u(s)\|^2 + C \|F(s, 0)\|^2. \tag{61}$$

Integrating both sides of (61) over $[0, t]$ yields

$$\|u(t)\|^2 \leq C \int_0^t \|u(s)\|^2 ds + C \int_0^t \|F(s, 0)\|^2 ds \leq C \int_0^t \|u(s)\|^2 ds + C. \tag{62}$$

Applying Gronwall’s lemma to (62) yields

$$\|u(t)\|^2 \leq C. \tag{63}$$

Now using Assumptions 2.1, 3.1, (63), the fact that $u \in C([0, T], H)$ and the stability properties of the two parameters semigroup yields

$$\begin{aligned} \|(-A(0))^{\frac{\beta}{2}} u(t)\| &\leq \|(-A(0))^{\frac{\beta}{2}} U(t, 0)u_0\| + \int_0^t \|(-A(0))^{\frac{\beta}{2}} U(t, s)F(s, u(s))\| ds \\ &\leq \|(-A(0))^{\frac{\beta}{2}} U(t, 0)(-A(0))^{-\frac{\beta}{2}}\|_{\mathcal{L}(H)} \|(-A(0))^{\frac{\beta}{2}} u_0\| \\ &\quad + \int_0^t \|(-A(0))^{\frac{\beta}{2}} U(t, s)\|_{\mathcal{L}(H)} \|F(s, u(s))\| ds \\ &\leq C + \int_0^t (t-s)^{-\frac{\beta}{2}} \|u(s)\| (1 + \|u(s)\|_C^1) ds \\ &\leq C + C \int_0^t (t-s)^{-\frac{\beta}{2}} ds \leq C. \end{aligned} \tag{64}$$

This completes the proof of the lemma. ■

Theorem 3.2. *Let $u(t)$ and $u^h(t)$ be solution of (9) and (14) respectively. Let Assumption 3.1 be fulfilled. If $u_0 \in \mathcal{D}((-A(0))^{\frac{\beta}{2}})$, then the following error estimate holds*

$$\|u(t) - u^h(t)\| \leq Ch^\beta, \quad t \in [0, T].$$

Proof. We introduce the following auxiliary equation

$$\frac{d\tilde{u}^h(t)}{dt} = A_h(t)\tilde{u}^h(t) + P_h F(t, u(t)). \tag{65}$$

Note that the mild solution of (65) is given by

$$\tilde{u}^h(t) = U_h(t, 0)P_h u_0 + \int_0^t U_h(t, s)P_h F(s, u(s)) ds, \quad t \in [0, T]. \tag{66}$$

Using triangle inequality, it holds that

$$\|u(t) - u^h(t)\| \leq \|u(t) - \tilde{u}^h(t)\| + \|\tilde{u}^h(t) - u^h(t)\|. \tag{67}$$

Let us start by estimating the first term in (67). Subtracting (66) from (10) and using triangle inequality, it holds that

$$\begin{aligned} \|u(t) - \tilde{u}^h(t)\| &\leq \|(U(t, 0) - U_h(t, 0)P_h) X_0\| \\ &\quad + \left\| \int_0^t (U(t, s) - U_h(t, s)P_h) F(s, u(s)) ds \right\| \\ &=: II_1 + II_2. \end{aligned} \tag{68}$$

Using Lemma 3.1 with $r = \alpha = \beta$ and Assumption 2.1 yields

$$II_1 \leq Ch^\beta \|(-A(0))^{\frac{\beta}{2}} X_0\| \leq Ch^\beta. \tag{69}$$

Using Lemma 3.1 (with $r = \beta$ and $\gamma = 0$), Assumption 3.1 and Lemma 3.2 yields

$$\begin{aligned} II_{21} &\leq Ch^\beta \int_0^t (t-s)^{-\frac{\beta}{2}} \|F(s, u(s))\| ds \leq Ch^\beta \int_0^t (t-s)^{-\frac{\beta}{2}} \|u(s)\| (1 + \|u(s)\|^{c_1}) ds \\ &\leq Ch^\beta \int_0^t (t-s)^{-\frac{\beta}{2}} ds \leq Ch^\beta. \end{aligned} \tag{70}$$

Substituting (69) and (70) in (68) yields

$$\|u(t) - \tilde{u}^h(t)\| \leq Ch^\beta, \quad t \in [0, T]. \tag{71}$$

Let us introduce the following error representation $\tilde{\tilde{e}}^h(t) := \tilde{u}^h(t) - u^h(t)$. It is obvious to see that $\tilde{\tilde{e}}^h(t)$ is differentiable with respect to the time and satisfies

$$\frac{d}{dt} \tilde{\tilde{e}}^h(t) - A_h(t) \tilde{\tilde{e}}^h(t) = P_h (F(t, u(t)) - F(t, u^h(t))), \quad t \in (0, T], \quad \tilde{\tilde{e}}^h(0) = 0. \tag{72}$$

Taking the inner product on both sides of (72), using (50) and Cauchy-Schwartz’s inequality yields

$$\begin{aligned} &\frac{1}{2} \frac{d}{ds} \|\tilde{\tilde{e}}^h(s)\|^2 - \langle A_h(s) \tilde{\tilde{e}}^h(s), \tilde{\tilde{e}}^h(s) \rangle_H \\ &= \langle F(s, \tilde{u}^h(s)) - F(s, u^h(s)), \tilde{\tilde{e}}^h(s) \rangle_H + \langle F(s, u(s)) - F(s, \tilde{u}^h(s)), \tilde{\tilde{e}}^h(s) \rangle_H \\ &\leq C \|\tilde{\tilde{e}}^h(s)\|^2 + C \|F(s, u(s)) - F(s, \tilde{u}^h(s))\| \|\tilde{\tilde{e}}^h(s)\|. \end{aligned} \tag{73}$$

Using Cauchy schwartz inequality, it follows from (73) that

$$\begin{aligned} &\frac{1}{2} \frac{d}{ds} \|\tilde{\tilde{e}}^h(s)\|^2 - \langle A_h(s) \tilde{\tilde{e}}^h(s), \tilde{\tilde{e}}^h(s) \rangle_H \\ &\leq C \|\tilde{\tilde{e}}^h(s)\|^2 + C \|F(s, u(s)) - F(s, \tilde{u}^h(s))\|^2 + C \|\tilde{\tilde{e}}^h(s)\|^2, \end{aligned} \tag{74}$$

Using the coercivity estimate (7), (74) and the fact that $\tilde{\tilde{e}}^h(s) \in V_h$ yields

$$\begin{aligned} \lambda_0 \|\tilde{\tilde{e}}^h(s)\|_1^2 &\leq a(s) (\tilde{\tilde{e}}^h(s), \tilde{\tilde{e}}^h(s)) = - \langle A_h(s) \tilde{\tilde{e}}^h(s), \tilde{\tilde{e}}^h(s) \rangle_H \\ &= - \frac{1}{2} \frac{d}{ds} \|\tilde{\tilde{e}}^h(s)\|^2 + \frac{1}{2} \frac{d}{ds} \|\tilde{\tilde{e}}^h(s)\|^2 - \langle A_h(s) \tilde{\tilde{e}}^h(s), \tilde{\tilde{e}}^h(s) \rangle_H \\ &\leq - \frac{1}{2} \frac{d}{ds} \|\tilde{\tilde{e}}^h(s)\|^2 + C \|\tilde{\tilde{e}}^h(s)\|^2 \\ &\quad + C \|F(s, u(s)) - F(s, \tilde{u}^h(s))\|^2 + C \|\tilde{\tilde{e}}^h(s)\|^2. \end{aligned} \tag{75}$$

Using (74), it holds that

$$\begin{aligned} & \frac{1}{2} \frac{d}{ds} \|\tilde{e}^h(s)\|^2 \\ & \leq C \|\tilde{e}^h(s)\|^2 + C \|F(u(s)) - F(\tilde{u}^h(s))\|^2 + C \|\tilde{e}^h(s)\|_1^2 + \langle A_h(s)\tilde{e}^h(s), \tilde{e}^h(s) \rangle_H \\ & \leq C \|\tilde{e}^h(s)\|^2 + C \|F(s, u(s)) - F(s, \tilde{u}^h(s))\|^2 + C \|\tilde{e}^h(s)\|^2 + \langle A_h(s)\tilde{e}^h(s), \tilde{e}^h(s) \rangle_H. \end{aligned} \tag{76}$$

Since $\tilde{e}^h(s) \in V_h$, using Cauchy-Schwartz’s inequality, the equivalence of norms [4, (2.12)] and [12, Lemma 3.1], it holds that

$$\begin{aligned} \langle A_h(s)\tilde{e}^h(s), \tilde{e}^h(s) \rangle & = \left\langle (-A_h(s))^{\frac{1}{2}}\tilde{e}^h(s), (-A_h(s)^*)^{\frac{1}{2}}\tilde{e}^h(s) \right\rangle_H \\ & \leq \frac{1}{2} \left\| (-A_h(s))^{\frac{1}{2}}\tilde{e}^h(s) \right\|^2 + \frac{1}{2} \left\| (-A_h(s)^*)^{\frac{1}{2}}\tilde{e}^h(s) \right\|^2 \\ & \leq \frac{C}{2} \|\tilde{e}^h(s)\|_1^2 + \frac{1}{2} \|(A_h^*)^{\frac{1}{2}}(-A_h(s))^{-\frac{1}{2}}\|_{\mathcal{L}(H)}^2 \left\| (-A_h(s))^{\frac{1}{2}}\tilde{e}^h(s) \right\|^2 \\ & \leq \frac{C}{2} \|\tilde{e}^h(s)\|_1^2 + \frac{C}{2} \left\| (-A_h(s))^{\frac{1}{2}}\tilde{e}^h(s) \right\|^2 \leq C \|\tilde{e}^h(s)\|_1^2. \end{aligned} \tag{77}$$

Substituting (77) in (76) and using (75) yields

$$\begin{aligned} \frac{1}{2} \frac{d}{ds} \|\tilde{e}^h(s)\|^2 & \leq C \|\tilde{e}^h(s)\|^2 + C \|F(s, u(s)) - F(s, \tilde{u}^h(s))\|^2 + \frac{C}{\lambda_0} \lambda_0 \|\tilde{e}^h(s)\|_1^2 \\ & \leq C \|\tilde{e}^h(s)\|^2 + C \|F(s, u(s)) - F(s, \tilde{u}^h(s))\|^2 - \frac{C}{2\lambda_0} \frac{d}{ds} \|\tilde{e}^h(s)\|^2. \end{aligned} \tag{78}$$

Therefore, from (78) we have

$$\left(\frac{1}{2} + \frac{C}{2\lambda_0}\right) \frac{d}{ds} \|\tilde{e}^h(s)\|^2 \leq C \|\tilde{e}^h(s)\|^2 + C \|F(s, u(s)) - F(s, \tilde{u}^h(s))\|^2. \tag{79}$$

Integrating both sides of (79) over $[0, t]$ yields

$$\|\tilde{e}^h(t)\|^2 \leq C \int_0^t \|\tilde{e}^h(s)\|^2 ds + C \int_0^t \|F(s, u(s)) - F(s, \tilde{u}^h(s))\|^2 ds. \tag{80}$$

Using the Cauchy-Schwartz’s inequality, Assumption 3.1, Lemma 3.2 and (71) yields

$$\begin{aligned} \|\tilde{e}^h(t)\|^2 & \leq C \int_0^t \|\tilde{e}^h(s)\|^2 ds + C \int_0^t \|F(s, u(s)) - F(s, \tilde{u}^h(s))\|^2 ds \\ & \leq C \int_0^t \|\tilde{e}^h(s)\|^2 ds + C \int_0^t \|u(s) - \tilde{u}^h(s)\|^2 (1 + \|u(s)\|^{2c_1} + \|\tilde{u}^h(s)\|^{2c_1}) ds \\ & \leq C \int_0^t \|\tilde{e}^h(s)\|^2 ds + Ch^{2\beta}. \end{aligned} \tag{81}$$

Applying the Gronwall’s lemma to (81) yields

$$\|\tilde{e}^h(t)\| \leq Ch^\beta, \quad t \in [0, T]. \tag{82}$$

This completes the proof of Theorem 3.2. ■

Remark 3.3. Along the same lines as in Theorem 3.2, one can obtain the error analysis in the following form

$$\|u(t) - u^h(t)\| \leq Ch^2 t^{-1+\beta/2} + Ch^2 (1 + \ln(t/h^2)), \quad t \in [0, T]. \tag{83}$$

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