

Microstructural and interface properties of aluminium alloy coatings on alumina applied by friction surfacing

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Abstract

Two large groups of materials, namely metals and ceramics, are used in mass quantities in today's industry because of their outstanding properties. To achieve higher product performance dissimilar materials need to be combined in assemblies, but their joining is challenging. Using friction surfacing technology Al₂O₃ ceramic substrates were coated with an aluminium alloy (AlMg4.5Mn0.7). Earlier research by the authors suggested that two major bonding mechanisms, namely mechanical interlocking and van der Waals forces, are responsible for the bonding strengths achieved between the coating and the substrate. Further SEM, STEM, HRTEM and EDX analyses at a sub nanometer resolution were conducted and are presented in this paper. These analytical methods revealed that the aluminium coating and the Al₂O₃ grains form a sharp boundary without evidence of either a chemical reaction or diffusion at the interface and suggest that the main bonding mechanisms for the Al/Al₂O₃ system are van der Waals forces. In addition, mechanical interlocking may serve to hold in position the interface surfaces, to preserve their close proximity, allowing the van der Waals forces to persist.

Keywords: friction surfacing, friction coating, aluminium alloy, alumina, ceramics, van der Waals, mechanical interlocking

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23 1. Introduction

24 Increasing demands for high performance materials leads to a sustained pressure for the devel-
25 opment of new materials, pushing physical and mechanical limitations to new levels. Parts with
26 locally differentiated material properties allow a tailored adaptation to the desired application pro-
27 files. Designs may require components to be fixed in specific locations or combined with other
28 parts. According to Martinsen et al. [1] dissimilar materials with different properties are jointly
29 used to achieve higher product performance in several industries already (e.g. automotive, aero-
30 nautics, marine applications). But joining these dissimilar materials, for instance ceramics with
31 metals, for further use in assemblies is challenging [2]. Metallized ceramics find their largest field
32 of application in electrical engineering, e.g. as insulators, diffusion pumps, thyristor and diode
33 housings. Joining these dissimilar materials is difficult and technologies currently used are com-
34 plex and relatively costly. According to Asthana and Sobczak [3] coating-substrate adhesion is
35 promoted by wettability and develops physical, chemical and mechanical interactions. Chemical
36 reactions at the surface are especially difficult to achieve for ceramic materials, due to their strong
37 ionic-covalent bonding types (e.g. Al_2O_3 mostly ionic, Si_3N_4 mostly covalent) which hold the
38 atoms together [4]. Whereas ceramic coatings applied on metal substrates serve the purpose of
39 modifying the surface structure for increased wear resistance and hardness [5], metal coatings ap-
40 plied to ceramic substrates provide an intermediate adhesion layer affording a means to bond with
41 new layers or other parts.

42 In this research work a new low-cost, reliable and robust coating technique for ceramics based
43 on friction surfacing (FS) was developed. Friction surfacing is a coating method in which, pre-
44 dominantly, metal substrates are coated with metals [14]. In earlier work by the authors [6] ce-
45 ramic substrates (Al_2O_3) were coated with an aluminium alloy (AlMg4.5Mn0.7) generating coating
46 thicknesses of $200\mu\text{m}$ and bonding strengths of 47MPa . Initial tests revealed that the interface tem-
47 perature can reach up to approximately 580°C . At this temperature the coating material, which was
48 in a viscoplastic state, flowed into the pores forming mechanical bonds by interlocking. This was
49 calculated to account for 16% of the bonding strength [6]. One may come to the assumption that by
50 the viscoplastic flow of the aluminium coating moving into the pores of the substrate air could be
51 pressed out of the cavities and create a pressure difference to the surrounding atmosphere causing
52 adhesion through suction. Experiments conducted by Budgett [7], bringing two metal surfaces in
53 close contact in vacuum, refute this theory concluding that molecular attraction is the main driving

54 force for adhesion. This is also confirmed for ceramic-metal interfaces in a recent publication by
55 Miyoshi and Abel [8] stating that when a clean metal is brought into contact with a clean ceramic
56 surface in ultrahigh vacuum, strong bonds between the two materials form. Popov [9], Lipkin et al.
57 [10] and Deng et al. [11] try to quantify the bonding mechanisms in metal-ceramic systems and
58 come to the conclusion that: as the interface surfaces may be in very close proximity van der Waals
59 forces could come into play, so contributing to metal-ceramic adhesion. To date, friction surfacing
60 of ceramics has seen little research attention, except for one article in a trade magazine of The
61 Welding Institute (TWI) in Abington, Cambridge UK [12] and a recently published article in the
62 peer-reviewed journal Coatings [13]. TWI [12] describes the successful deposition of aluminium
63 onto an alumina substrate on their webpage. These tracks of aluminium are only a few millimetres
64 wide and less than 50 μ m thick. A similar approach was used by Chmielewski et al. [13], investigat-
65 ing the properties of titanium (Ti) coatings on an aluminium nitride (AlN) substrate deposited by
66 friction surfacing. Coating thicknesses up to 7 μ m were reported as having been achieved. Friction
67 surfacing of large surface areas or reports of achieving a coating thickness in the millimetre range,
68 so producing material composites, is not as yet possible. There are no known publications in this
69 area other than what is listed here.

70 In the friction surfacing process, a rotating disc or rod of coating material is pressed against
71 a substrate surface. The heat generated by friction weakens the bonds between the atoms and
72 decreases the yield strength [15]. This leads to a change in the flow properties of the coating
73 material (i.e. plasticisation). The introduction of relative transverse motion along the substrate
74 surface results in material being deposited [16]. The generated heat and applied pressure leads to
75 the formation of new bonds between the two materials. Figure 1 shows a coated Al₂O₃ specimen
76 with the matching rod.

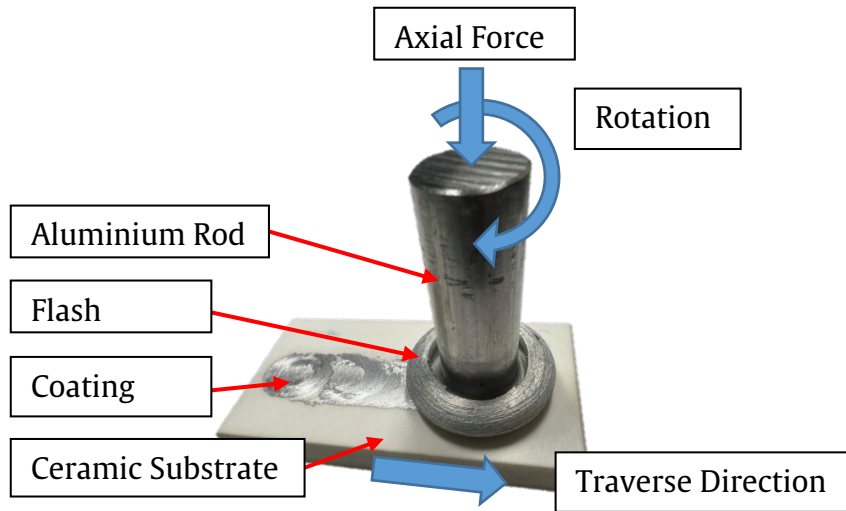


Fig. 1. Friction surfaced Al_2O_3 specimen.

77 Friction surfacing of ceramics is a simple and fast coating process. Short coating times enable
 78 the process to be integrated within automated production lines. Thick layers can be produced in
 79 seconds and realise bonding strengths similar to current metallizing methods such as magnetron
 80 sputtering (i.e. physical vapour deposition) [23] and thermally sprayed coatings [24].

81 A review publication by Gandra et al. [14] gives a broad insight into the topic of friction surfac-
 82 ing and acting mechanisms. Achieved bonding types differ significantly, depending on the process
 83 parameters and material combination used. According to Bedford et al. [17] the bond between high
 84 speed steel coatings and carbon steel substrates applied by friction surfacing is formed by diffusion.
 85 This is a result of the force applied and the temperature reached at the interface. Looking at com-
 86 binations of dissimilar materials with different strengths, mechanical interlocking can occur. The
 87 applied force and temperature can deform the substrate in such a way that the coating rod forms
 88 dovetail shaped indentations on the surface and creates a bond by interlocking structures [18]. In-
 89 terlocking can also occur when the coating material, in its visco-plastic state, flows into the pores
 90 of the substrate forming anchor-points. In the work of Chandrasekaran et al. [19] who studied the
 91 interface of mild steel substrates coated with Inconel alloys, evidence of reaction products forming
 92 at the interface can clearly be seen in microscope images. It is stated that these chemical bonds in-
 93 crease the bonding strength significantly. As described by Butt et al. [20] this is the most effective
 94 bonding mechanism, with bonding strengths that are usually excellent; this can also be desirable for

95 friction surfaced coatings. Despite the fact that van der Waals forces are not mentioned in friction
96 surfacing publications it plays a major role in ceramic-metal interfaces [11, 21]. These forces arise
97 whenever two materials come in close contact with each other and result from dipole interactions.
98 It is important to know that they also act between different materials and depend only on the contact
99 distance, making them universal in interaction [22].

100 The research described in this paper aimed to determine the prevailing bonding mechanism for
101 when alumina is friction surfaced with an aluminium alloy.

102 2. Experimental setup and method

103 The experimental setup is shown in Figure 2. A standard milling machine (DMG Mori Co.,
104 Germany, Model: Maho MH700) was adapted to apply metal coatings onto ceramic substrates.

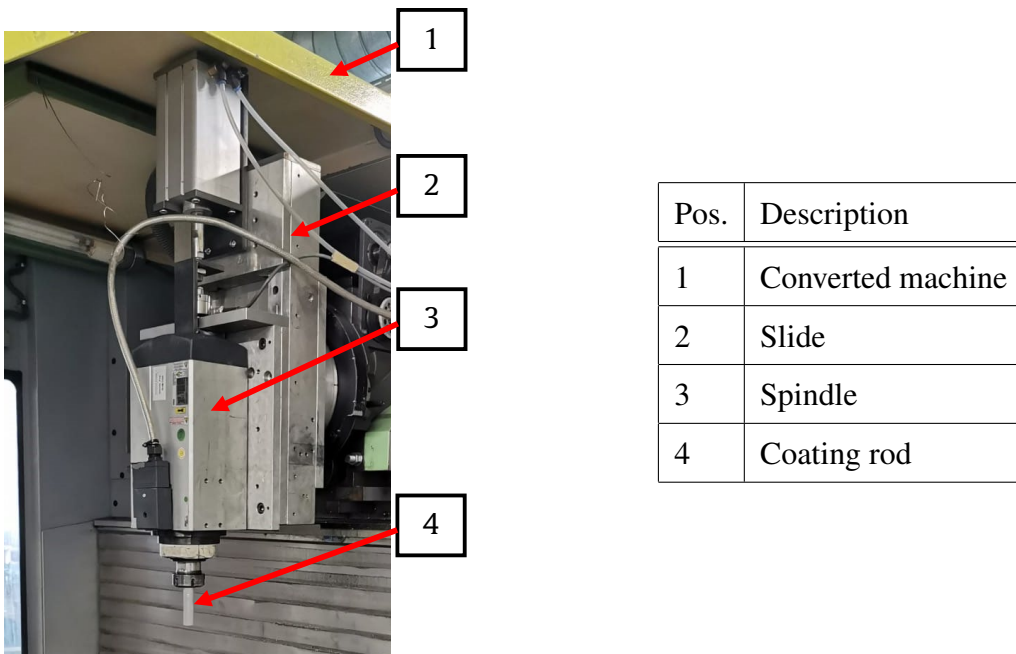


Fig. 2. Experimental setup.

105 To clamp the ceramic substrates a special clamping device was designed and manufactured (see
106 Figure 3) [25].

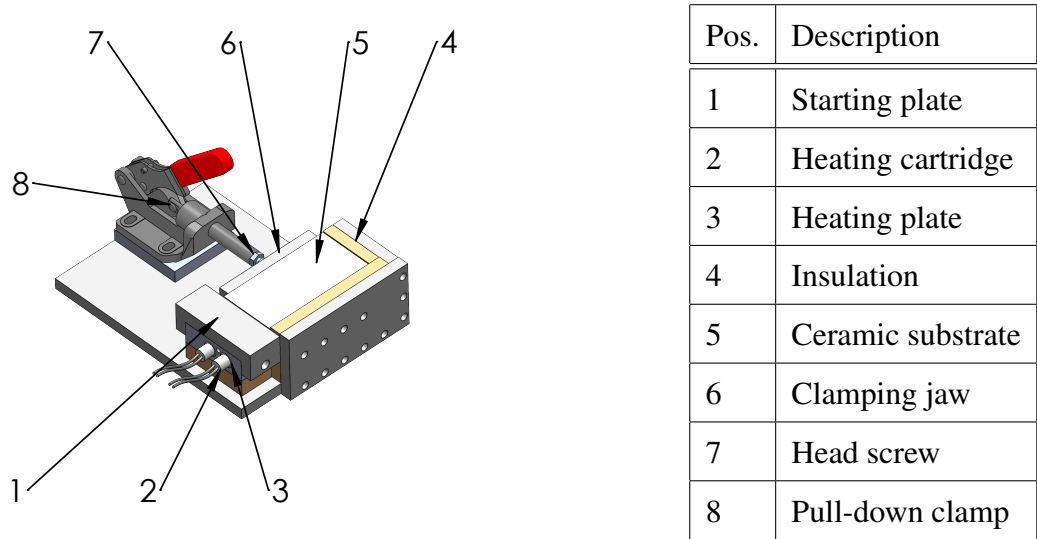


Fig. 3. Clamping device design.

107 Jahanmir [26] gives an overview of ways and means of machining and clamping ceramic mate-
 108 rials. He states that when clamping ceramics the specific characteristics of the material have to be
 109 taken into account as local load peaks could induce cracking. Thus, for better force distribution the
 110 ceramic substrate was clamped on the long side using a pull-down clamp locked into a clamping
 111 jaw.

112 In previous work by the authors micro-cracking in the substrate caused by thermal shock was
 113 observed [6]. It was noted that an abrupt increase in temperature can lead to a higher thermal
 114 stress causing substrate failure. To reduce the thermal shock on the ceramic substrate the process
 115 of pressing the rotating coating rod was initiated directly on the substrate; which was in contrast to
 116 previous work, where a *starting plate* was employed.

117 Figure 4a and Figure 4b shows two thermal profiles with and without the use of a starting plate.

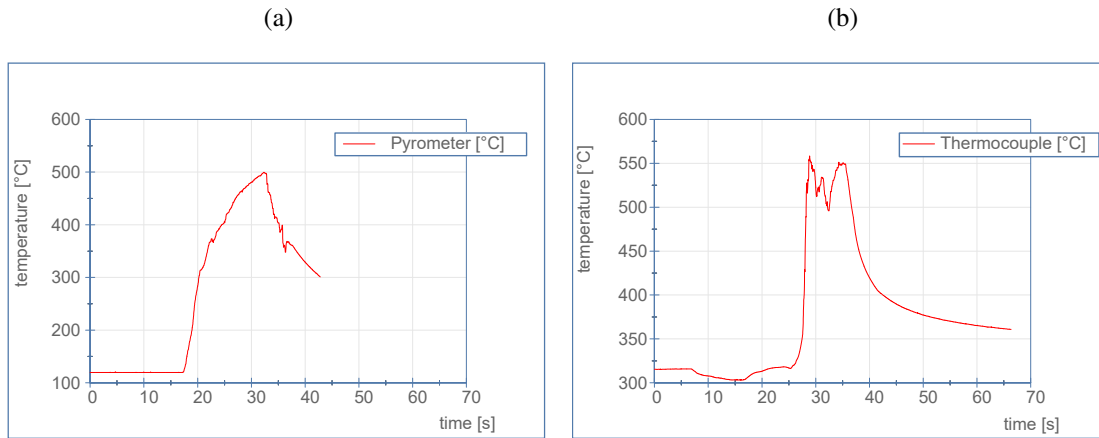


Fig. 4. Thermal profiles of specimens coated (a) without the use of a starting plate and (b) with the use of a starting plate.

118 For the first test (see Figure 4a) the temperature was recorded with the use of a pyrometer aimed
 119 at the interface between the coating rod and the substrate. For the second test shown in Figure 4b
 120 a thermocouple was embedded at the surface of the substrate. It can be seen that the increase in
 121 temperature for the specimen without the use of a starting plate (Figure 4a) is slower over time
 122 leading to an additional heating of the substrate. Whereas the temperature rise for the specimen
 123 with the use of a starting plate (Figure 4b) is sharp and abrupt. Thus, the use of a starting plate was
 124 omitted for this parametric study.

125 Also, preliminary tests revealed that preheating the specimens to a temperature of 150°C re-
 126 duced the probability of fracture. Thus, two high performance heating cartridges (Tuerk & Hillinger
 127 GbmH, Germany, Model: HLP 125099) were used to preheat the specimens.

128 2.1. Material selection and preparation

129 It is desirable that the coating material should be a weldable alloy which would allow for joining
 130 assemblies in subsequent processes. According to Ostermann [27] the weldability, corrosion resis-
 131 tance and ductility of the EN AW-5xxx group of alloys is excellent. In addition, the chosen alloy,
 132 EN AW-5083 (AlMg4.5Mn0.7) has a high strength with the manganese and magnesium content
 133 supporting chemical bonding by forming $MnAl_2O_4$ and $MgAl_2O_4$ spinel at the interface.

134 For the substrate material Al_2O_3 was chosen. Aluminium oxide is one of the most widely used
 135 technical ceramics [28]. Due to its high corrosion resistance it is used in the chemical industry for

136 corrosion protection and furnace lining [29]. It is well known for its good mechanical properties
137 and thermal stability. It shows temperature resistance up to 1850°C and at the same time exhibits
138 excellent fracture and wear resistance with high stiffness [30]. Larger quantities are readily avail-
139 able and inexpensive to obtain.

140 For the experiments aluminium alloy rods with dimensions of $\varnothing 20 \times 80$ mm as a coating
141 material, and 92% alumina plates (i.e. 92% pure Al_2O_3 and 8% additives) as a substrate material
142 with dimensions of $150 \times 50 \times 13$ mm were used. The ceramic substrate surfaces were ground and
143 chamfered. Before starting the coating process all material surfaces were degreased.

144 3. Results and Discussion

145 Results on achieved coating thicknesses and bonding strengths were published in earlier work
146 by the current authors [6]. This section will give an insight into the acting bonding mechanisms.

147 It was reported that temperatures can reach up to approximately 580°C during the coating pro-
148 cess. Analysis of the interface showed no clear evidence for intermetallic compounds with investi-
149 gations turning towards van der Waals forces as the main source for the achieved bonding strength.
150 These forces can be calculated by determining the distance between the two close-contact bodies
151 [31] and for two flat surfaces the following equation can be used [32, 33]:

$$P(D) = \frac{H}{6 \cdot \pi \cdot D^3} \quad (1)$$

152 where $P(D)$ is the bonding strength, H is the Hamaker constant and D the distance between the
153 two surfaces.

154 The Hamaker constant is a coefficient relating to the force between particles interacting through
155 van der Waals forces [34], it is dependent on the materials in contact and the separation medium.
156 It assesses the magnitude of the van der Waals interactions whereby the van der Waals forces are
157 directly proportional to the Hamaker constant (see equation 1). According to Bergström [35] the
158 Hamaker constant can be estimated by the dielectric properties of the interacting materials and the
159 separation medium. Unknown Hamaker constants can be approximated by combining known ones
160 by employing equation [32]:

$$H_{132} = (\sqrt{H_{11}} - \sqrt{H_{33}})(\sqrt{H_{22}} - \sqrt{H_{33}}) \quad (2)$$

$$H_{132} = \sqrt{H_{11} \cdot H_{22}} \quad (3)$$

161 where H_{11} is the Hamaker constant of material one, H_{22} of material two, H_{33} of the medium
 162 separating the two materials and H_{132} is the combined constant. Note that the Hamaker constant
 163 for a vacuum and air is zero, and thus the Hamaker constant for the separation medium H_{33} may be
 164 dropped from the equation.

165 The Hamaker constants for Al_2O_3 and molten aluminium can be taken from literature (i.e.
 166 $H_{\text{Al}_2\text{O}_3} = 140 \cdot 10^{-21} \text{ J}$ [36], $H_{\text{Al}} = 266 \cdot 10^{-21} \text{ J}$ [37]); with $H_{\text{Al}/\text{Al}_2\text{O}_3}$ calculated from equation 3 as
 167 $254 \cdot 10^{-21} \text{ J}$.

168 Using equation 1 and the combined Hamaker constant, the adhesion tension can be determined
 169 as a function of the separation distance: this was computed and plotted in Figure 5. First estimates
 170 of the van der Waals forces suggest that these interactions will manifest themselves at a nano-meter
 171 scale.

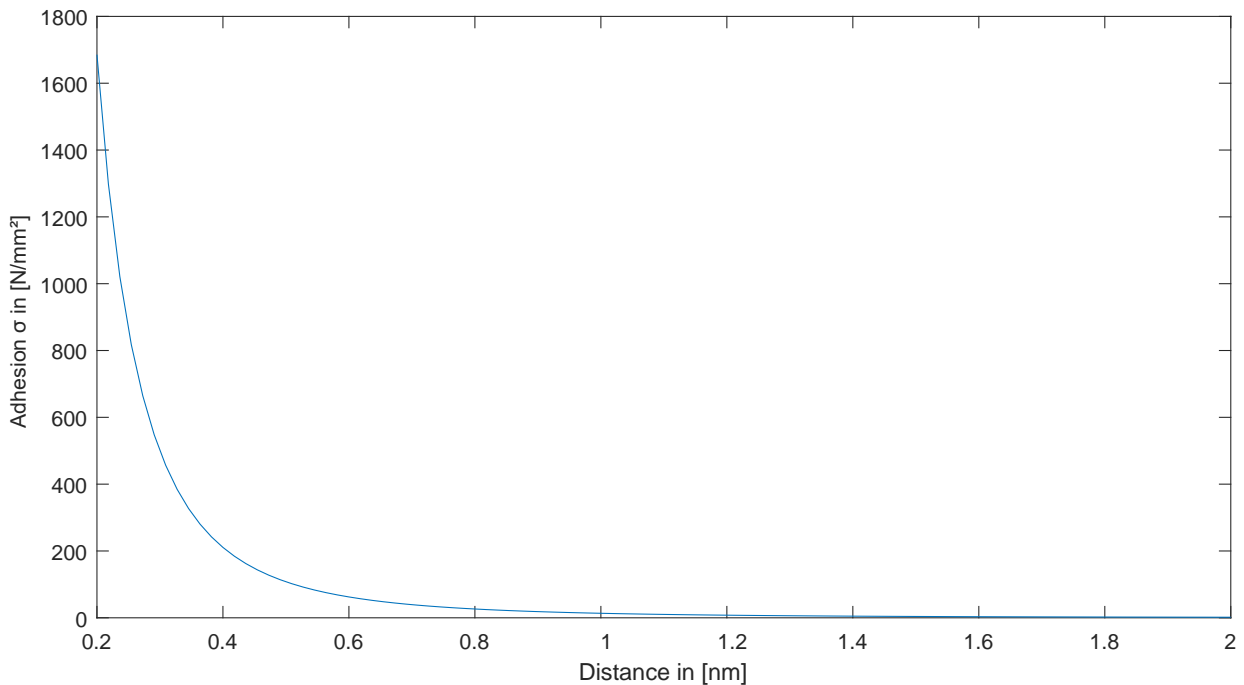


Fig. 5. Van der Waals forces.

172 Due to the combination of a hard and brittle material (Al_2O_3) and a ductile material (Al-alloy),

173 preparation of specimens to allow inspection of the interface was found to be challenging. When
174 polishing, smearing of the aluminium onto the alumina substrate was an issue making it difficult
175 to analyse the interface properly. Therefore, specimens were prepared by using a combination
176 of a focused ion beam milling instrument with a scanning electron microscope (FIB-SEM), and
177 analysed for occurring elements by Energy-dispersive X-ray spectroscopy (EDX). Specimens of
178 different density and ductility were prepared without smearing, and surfaces were polished by
179 milling at a nanometre scale.

180 For SEM imaging and EDX analysis a Zeiss Auriga 60 with an Ametek EDAX Octane Elect+
181 Detector was used, whilst for FIB-SEM preparation and analysis a Zeiss NVision 40 was employed.

182 *3.1. Microscopic and EDX analysis*

183 Coated specimens have been cut, embedded in epoxy and ion milled for high-resolution imaging
184 which would not be possible by polishing the specimens using traditional methods alone. Figure
185 6a-6d shows the coated specimen after initial slicing for better handling and the cut-off part for
186 analysis. Figures 6e and 6f show the specimen before and after ion milling (IM), respectively. As
187 can be seen the surface structure of the specimen is much smoother after ion milling and shows a
188 more polished appearance. This is much more apparent at a microscopic level and was done to help
189 identify bonding mechanisms in greater detail.

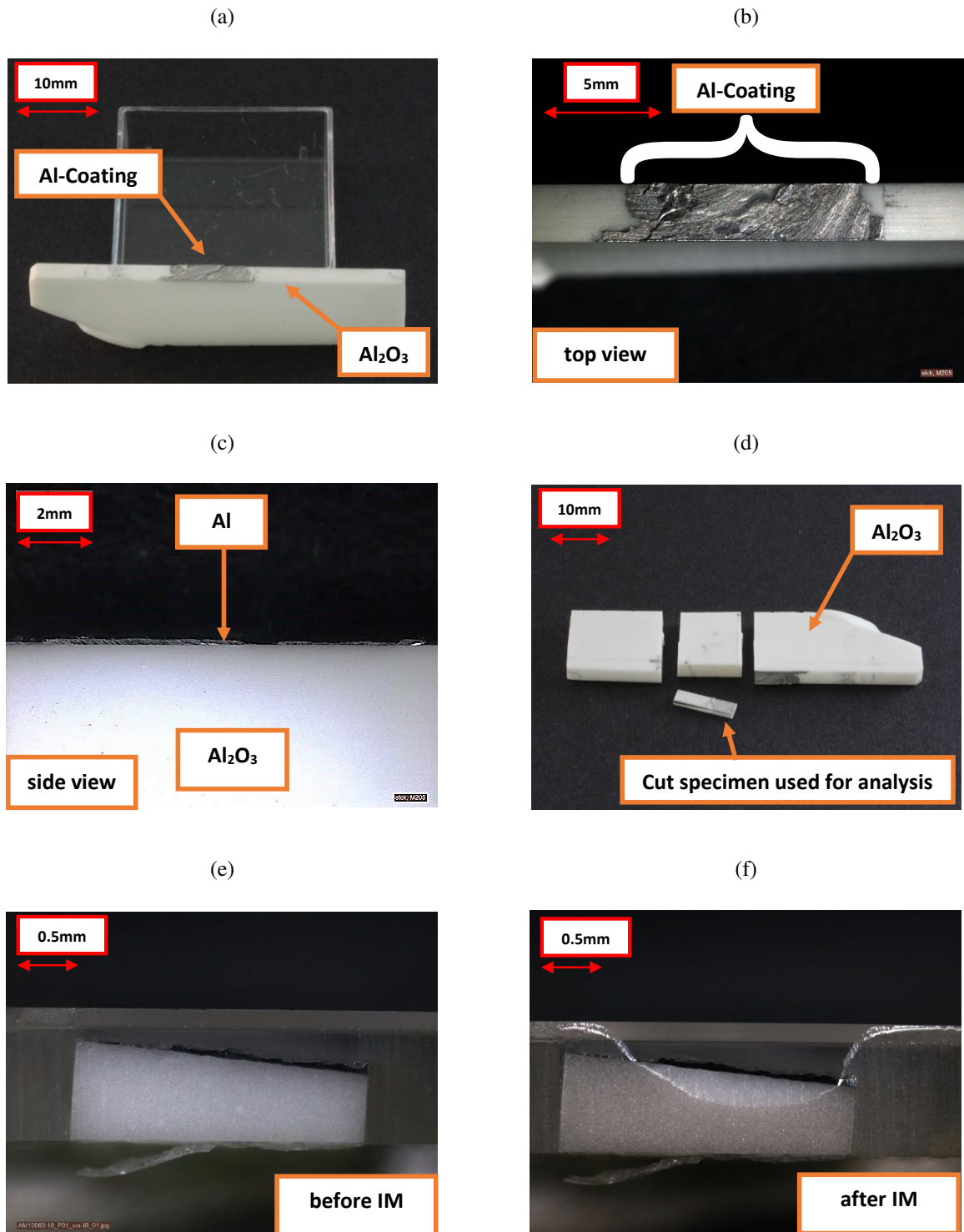


Fig. 6. Al_2O_3 specimen (a) after initial slicing, (b) top view before cutting, (c) side view before cutting, (d) cut specimen for analysis, (e) before and (f) after ion milling.

191 the LHS to the RHS of the image. Shifting the focus to the substrate, not only can individual
192 alumina grains be identified; but also the size and grain structure of the coating material is exposed.
193 Examining the coated layer it is apparent that the grain size near the surface of the coating is much
194 smaller than at the metal-ceramic interface. According to Bararpour et al. [38], and by way of
195 comparison - who studied thermal and mechanical reactions during friction surfacing of aluminium
196 alloy substrates using aluminium alloy rods for the coating, the prevailing high temperatures and
197 pressure leads to dynamic recrystallisation of the coating material. In this case, due to the high
198 cooling rates at the interface, a finer grain size can be observed at the interface than near the surface
199 at the top of the coating. This is in contrast with what was observed in *this* study. Because of
200 the low thermal conductivity of the Al_2O_3 substrate and the insulation surrounding the substrate in
201 the clamping device (see Figure 3), heat transfer is restricted beneath the ceramic substrate. The
202 surface of the coating, on the other hand, is in contact with the ambient air and can therefore radiate
203 heat leading to an abrupt temperature drop. As mentioned by Humphreys et al. [39] one major
204 factor affecting grain growth during dynamic recrystallisation is temperature and that "significant
205 grain growth is often found only at very high temperatures". Transferring this knowledge to the
206 conducted experiments it becomes evident that the temperature at the interface does not change
207 as abruptly as on the coating surface; giving more time for grain growth. A smaller grain size
208 may lead to an increase in tensile strength [40] of the coating material and will be part of future
209 investigations.

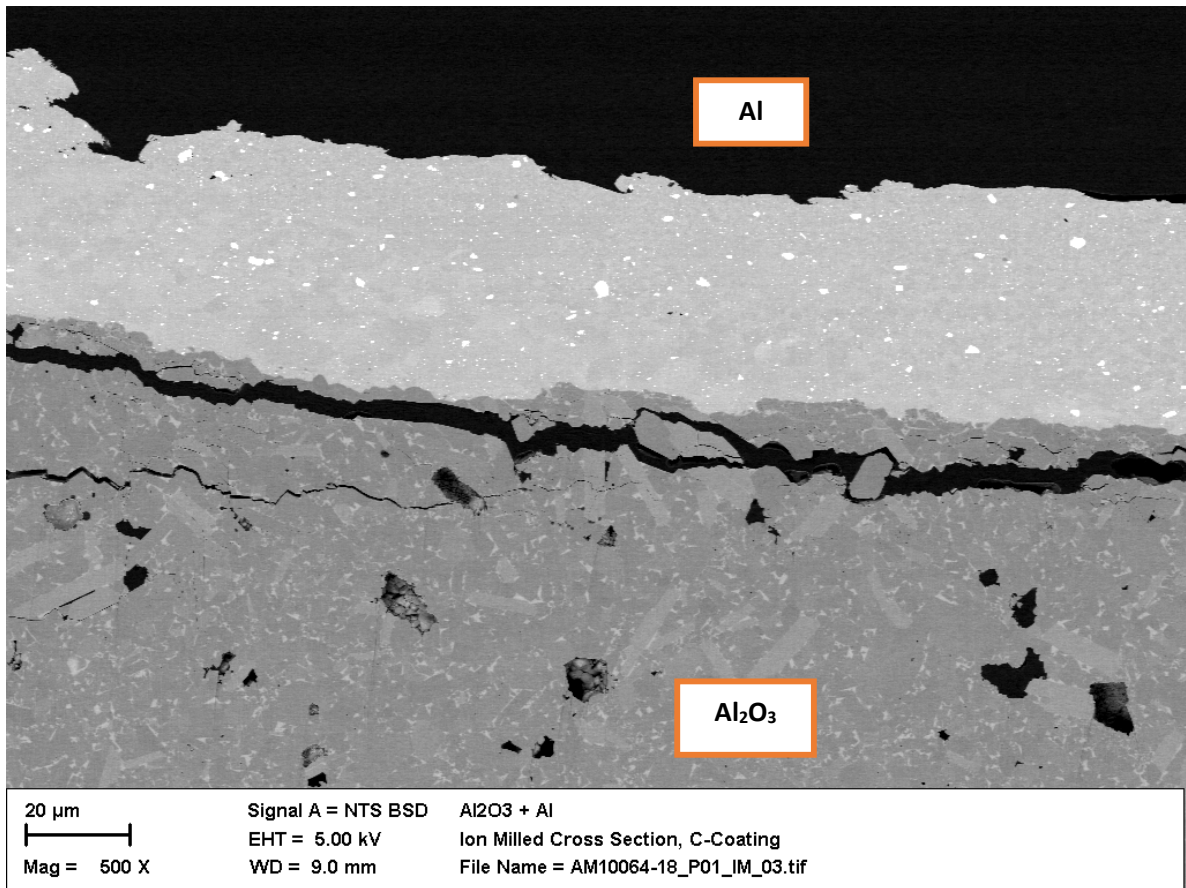


Fig. 7. Ion-milled cross section of Al₂O₃ + Al coating.

210 Examining the aluminium coating and ceramic substrate at different spots by EDX analysis
211 (Figure 8) reveals intermetallic compounds (i.e. Al₆(Fe,Mn)) as blocky particles present in the
212 aluminium alloy, an example of which can be identified at spot 2. These form due to the high Mn
213 content in the alloy and increase the strength of the material [41]. Also, magnesium oxide, silicon
214 oxide and calcium oxide (i.e. spot 5) accumulate at the grain boundaries of the ceramic substrate
215 (i.e. spot 3 shows a region of the substrate). These additives lower the sintering temperature and
216 are used during production [42].

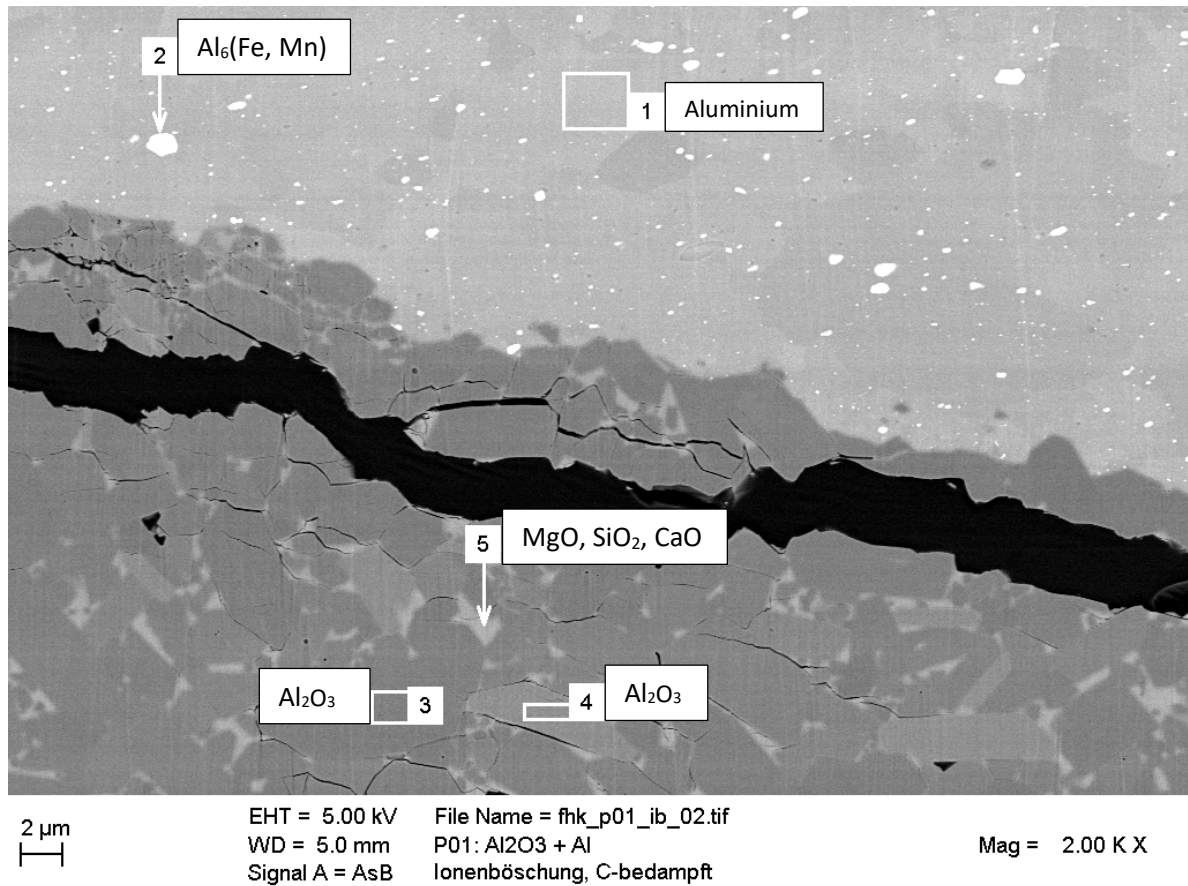


Fig. 8. Cross section of $\text{Al}_2\text{O}_3 + \text{Al}$ coating with marked EDX analysis spots.

217 According to Imanaka [43] these glassy-phases are used for metallizing Al_2O_3 with nickel
 218 by chemical reaction of the glassy-phases with the applied Mo-Mn-paste forming anchor points.
 219 Looking again at Figure 8 some grain boundaries are exposed to the aluminium coating and could
 220 react in the same fashion to form a solid bond between the glassy-phase and the metal. According
 221 to Berek et al. [44] who studied interfacial reactions of Al_2O_3 particle reinforced 6061 aluminium
 222 alloys, in their work no reaction products were found at the particle/matrix interfaces in the as-cast
 223 state. Consistent with these findings Zhou et al. [45], who studied interfacial reactions of metal-
 224 matrix composites consisting of alumina preforms infiltrated with aluminium-manganese-alloys,
 225 reaction products at the interface were found to be rare and that structureless interfaces between
 226 alumina and aluminium were a more typical occurrence. Similar studies by Yu et al. [46] confirm

227 these results. Using higher magnifications (Figure 9) no interfacial reactions are evident. The
228 sharp boundaries of the aluminium oxide grains are completely enclosed by aluminium showing
229 no evidence of a gap or reaction zone.

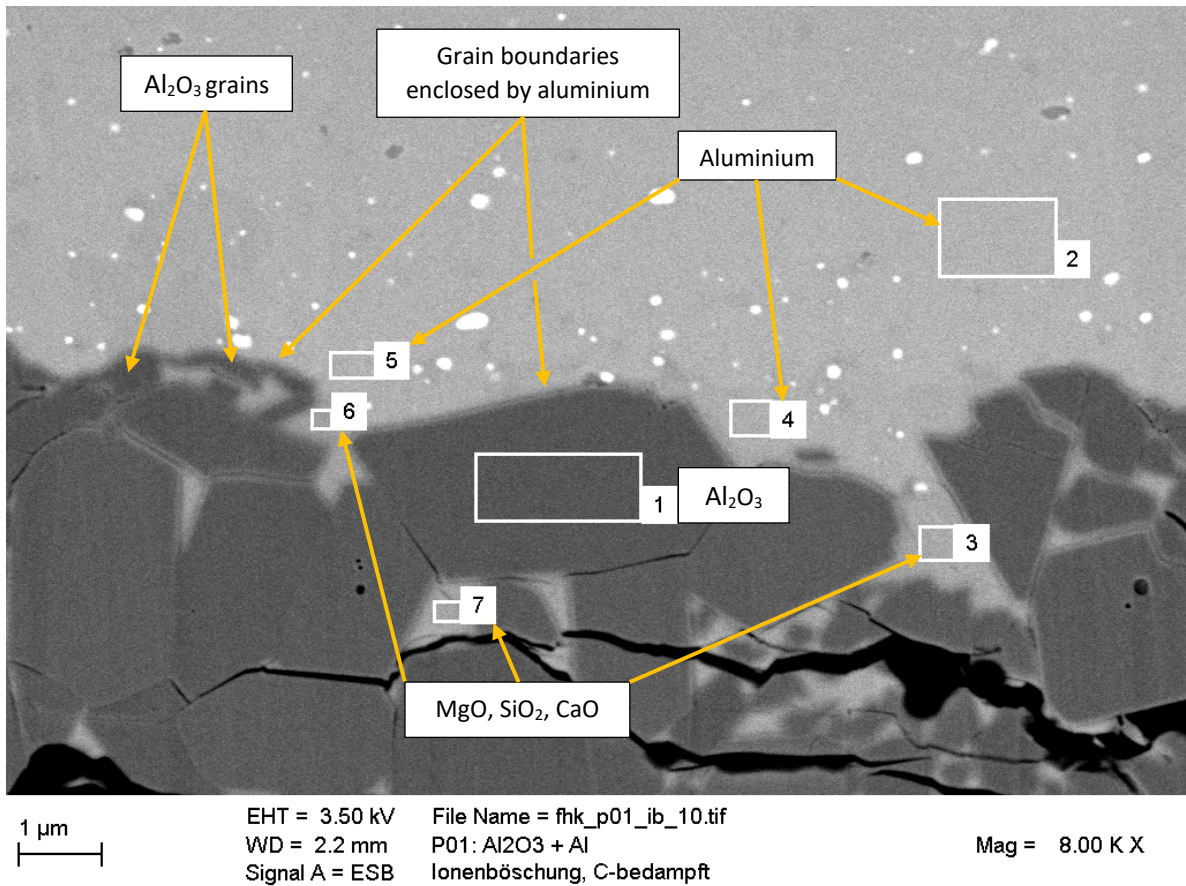


Fig. 9. Higher magnification image of aluminium oxide grains and boundaries.

230 Changing the contrast of the image serves to emphasise this point (Figure 10).

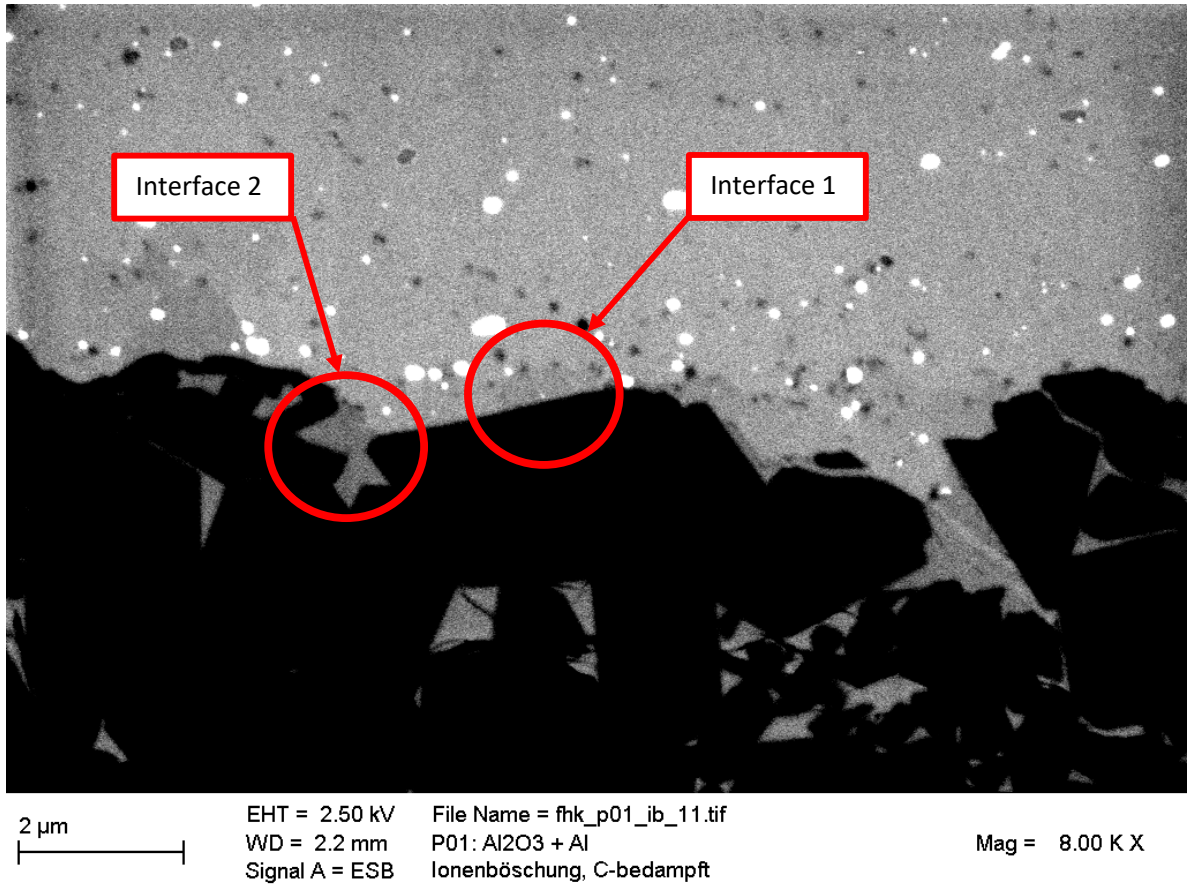


Fig. 10. High contrast image of aluminium oxide grains and boundaries.

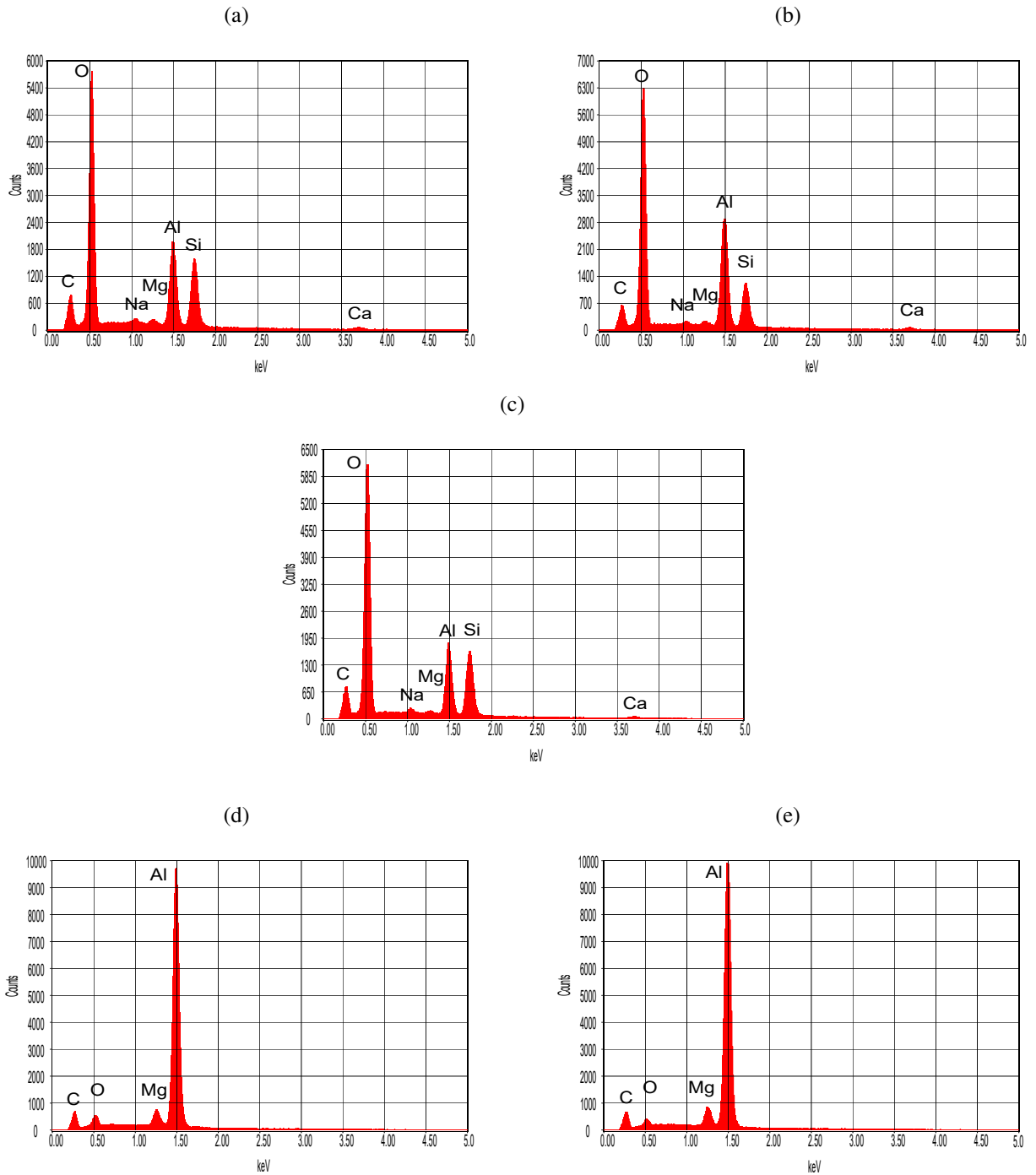


Fig. 11. EDX analysis of spots (a) 3, (b) 6, (c) 7, (d) 4 and (e) 5 shown in Figure 9.

231 EDX analysis at different locations was conducted (see Figure 9 for spot positions). Comparing
 232 spots 3, 6 and 7 (EDX profile in Figure 11a, 11b and 11c respectively) reveals that these areas are
 233 accumulations of sintering additives which form the glassy-phase; cross-checked at spots 4 and 5

234 (Figure 11d, 11e). Interestingly spot 3 and 6 have been exposed to the aluminium coating forming
235 a new interface. Shifting focus back to the higher contrast image (Figure 10) it can be seen that at
236 these spots the glassy-phase and the aluminium coating form a sharp edge distinguishable by the
237 darker and lighter grayscale, but show no reaction zone in between. This analysis of the interface
238 is in line with literature where no reaction zone between Al_2O_3 grains and aluminium could be
239 identified [45, 46].

240 Further transmission electron microscopy (TEM) analysis has been conducted to identify active
241 binding mechanisms. For this purpose a TEM (Carl Zeiss Libra 200 Cs, with an acceleration
242 voltage of 200 kV) was used. The integrated scanning transmission electron microscope (STEM)
243 and high resolution TEM (HRTEM) mode was used for imaging at higher magnifications. EDX
244 was performed on the sample using a detector from Oxford Instruments attached to the TEM.

245 To accommodate for the induced stress on the material during TEM preparation a specimen
246 with a high bonding strength was selected. Figure 12a shows a coated specimen, already cut to a
247 smaller size, with a bonding strength of 44.27 MPa. For TEM analysis samples must be prepared to
248 be as thin as possible (i.e. lamella), so that the electrons can pass through the sample for imaging.
249 This was done by using a FIB-SEM for cutting out the sample and polishing the specimen by ion
250 milling. The area marked in red (Figure 12b) was used to prepare the lamella.

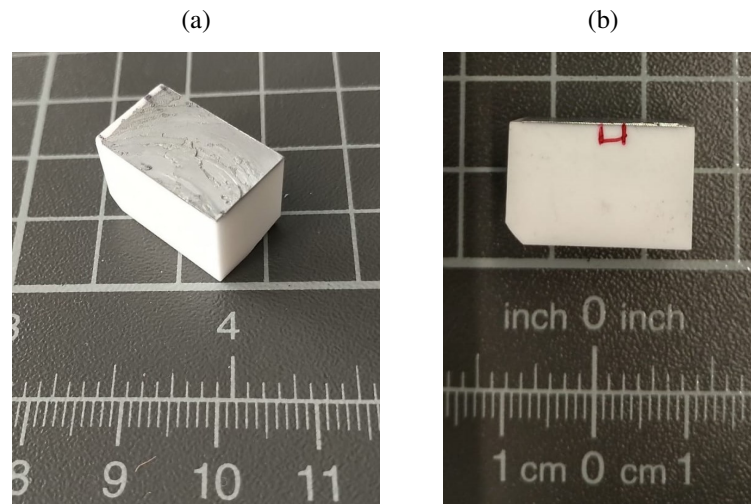


Fig. 12. (a) Image of coated specimen, and (b) marked area for lamella.

251 During the thinning process pores and cracks within the Al_2O_3 substrate and the aluminium part
252 were observed (see Figure 13a). Due to the internal stress and brittle nature of the specimen the

253 central region was reinforced by depositing platinum onto the frail surface. Further thinning down
254 of the specimen was carried out on the left and right side of the part.

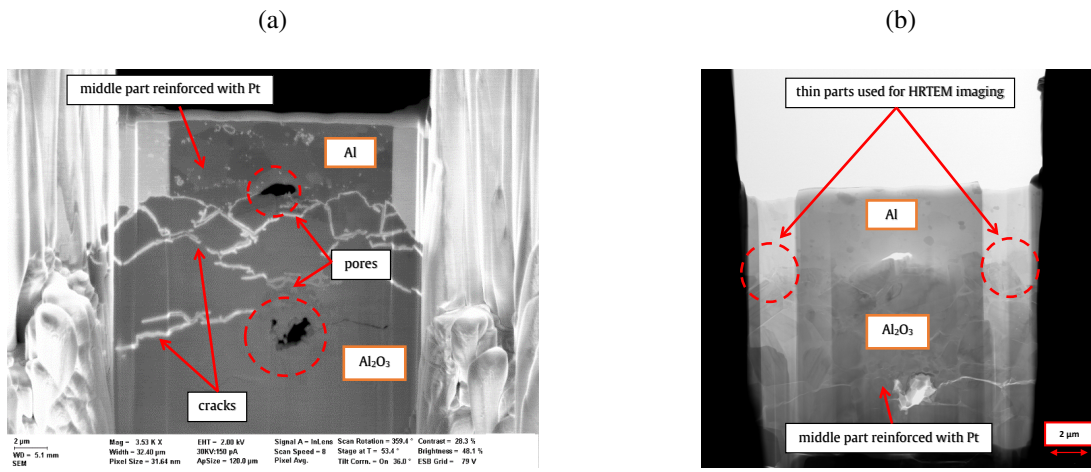


Fig. 13. (a) SEM image showing pores and cracks, and (b) STEM image showing thinned parts and region for HRTEM study.

255 Figure 13b shows a STEM image of the finished lamella with the marked area for the HRTEM
256 study. The left and right side of the specimen was thinned down to 50nm whereas the middle
257 part was used as reinforcement with a thickness of 100nm. By using HRTEM imaging the atomic
258 structure at the interface was examined in detail. Figures 14a and 14b show images of the Al₂O₃
259 grain boundary and aluminium interface. At a scale of 5nm no reaction zone is visible. The
260 lattice structure of the Al₂O₃ grains can be seen to change abruptly into the lattice structure of the
261 aluminium. Magnifying the interface to a 1nm scale (Figure 14c) the distance between the Al₂O₃
262 grain and the aluminium coating could not be identified, concluding that the separation distance is
263 lower than the scale factor.

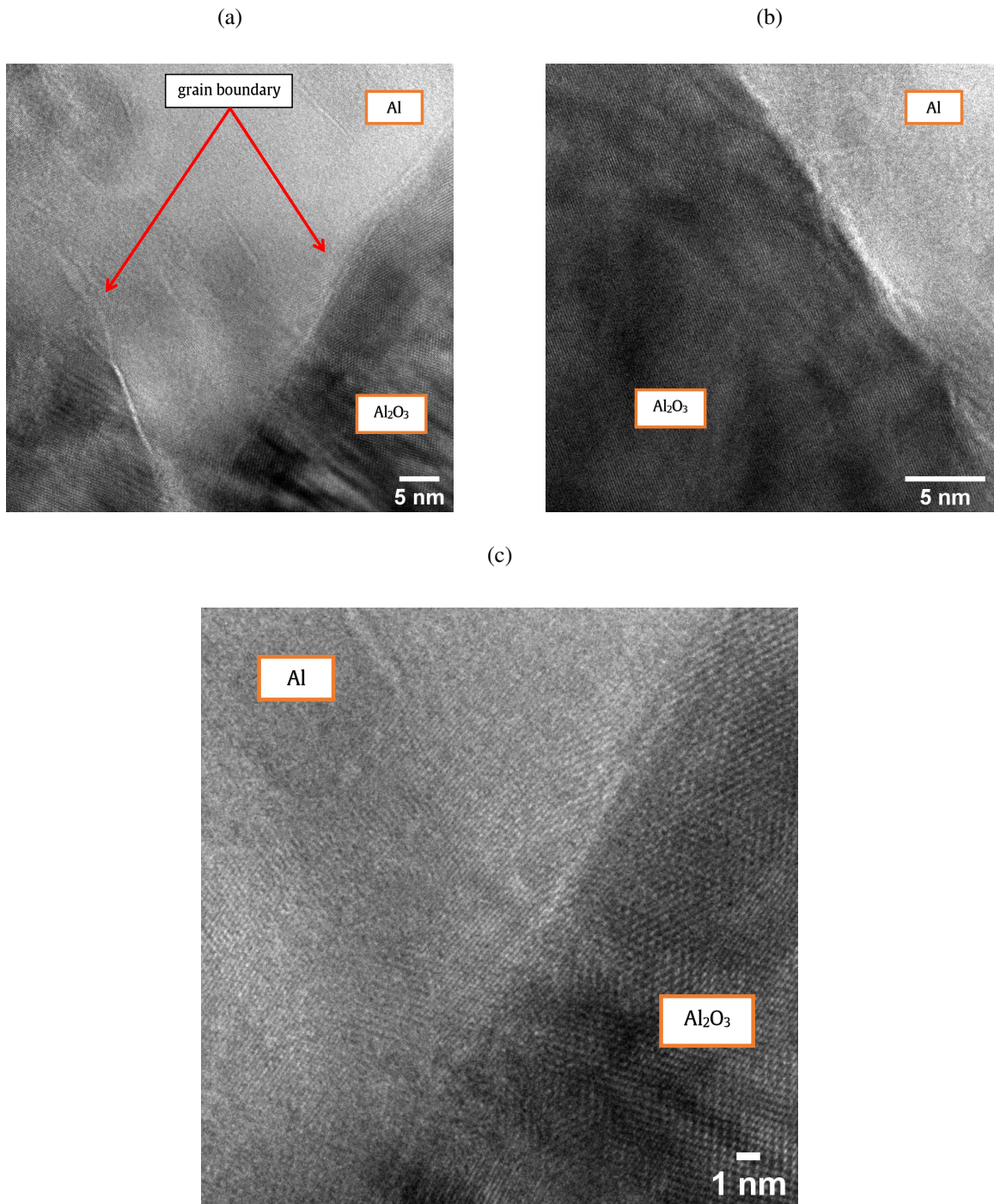


Fig. 14. HRTEM image of (a) aluminium between two Al₂O₃ grains, (b) different spot of aluminium and Al₂O₃ grain, and (c) magnification of interface.

264 One thing that stands out on closer inspection of the lattice structure is the partially amor-
265 phous state of the aluminium coating. According to Ojovan and Lee [47] liquid-glass transition

266 is observed in various types of liquids including metals. If the cooling rate is high enough crys-
267 tallisation can be avoided and the metal exhibits a disordered atomic structure. These amorphous
268 metals show higher strength and ductility than their lattice structured counterparts, but are difficult
269 to manufacture [48]. As reported by Suryanarayana [49] amorphous alloys can be produced by
270 mechanical alloying which is a processing technique involving repeated cold welding, fracturing
271 and rewelding of powder particles. Transferring this procedure to friction surfacing, a similar phe-
272 nomenon can be observed. The coating material is rubbed against the substrate surface where the
273 microscopic peaks and valleys make contact and form micro-bonds. Fracture of these micro-bonds
274 leads to heat generation and local melting of the material due to thermal spikes. Because of the
275 applied axial force, grains are crushed into finer grains and the partial melting of the material leads
276 to the dissolving of grain boundaries: dynamic recrystallization occurs. During deposition rapid
277 cooling of the quasi liquid layer takes place producing fine grains in the coating. The combination
278 of repeated crushing and recrystallizing of the grains, then rapid cooling at the interface, could lead
279 to forming of partially amorphous aluminium as show in Figure 15.

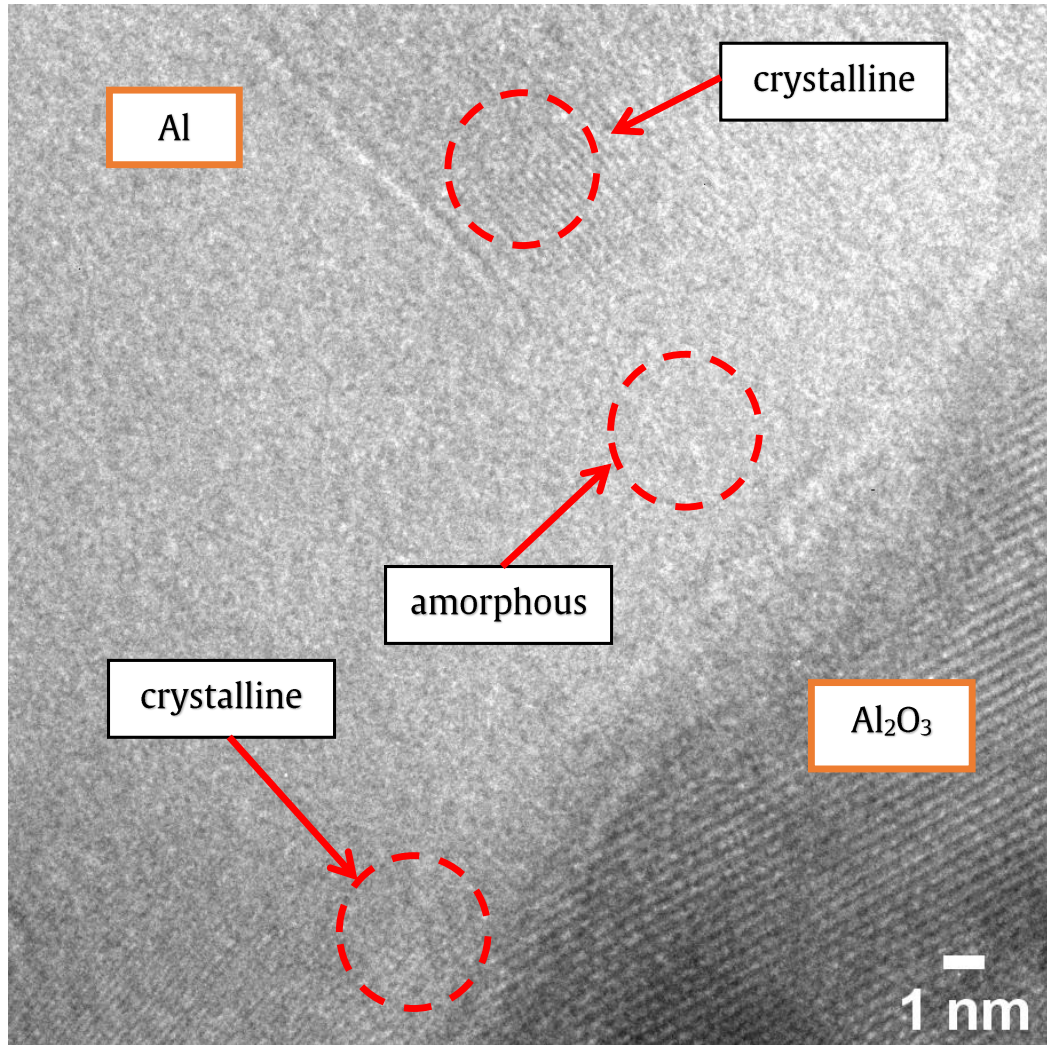


Fig. 15. Atomic structure of Al coating.

280 Reflecting on the findings above it can be said that van der Waals forces are the main binding
 281 mechanisms for the Al/Al₂O₃ system. Taking into account the mechanical interlocking portion of
 282 16% [6] and using equation 1 the distance D for a given bonding strength (e.g. 44.27 MPa) can be
 283 calculated as follows:

$$D = \sqrt[3]{\frac{H}{6 \cdot \pi \cdot P}} = \sqrt[3]{\frac{254 \cdot 10^{-21} [Nm]}{6 \cdot \pi \cdot [44.27 \cdot 10^6 [N/m^2]] \cdot (1 - 0.16)}} = 0.713 nm \quad (4)$$

284 Because of the reciprocal exponential relationship of the distance D to the bonding strength

285 $P(D)$ an increase in the separation distance will have an exponentially negative effect on the bonding
286 strength. It can be conjectured that the mechanical interlocking may serve to hold in position the
287 interface surfaces, to preserve their close proximity, allowing van der Waals force to persist. Also
288 interlocking may prevent transverse relative displacement between the two surfaces which would
289 prevent roughness in the contacting surfaces from increasing the separation distances. Even though
290 the pores only account for 16% of the bonding strength, their influence on the van der Waals forces
291 and their persistence should not be underestimated.

292 4. Conclusion

293 In earlier experiments alumina specimens were coated with aluminium showing encouraging
294 results for the achieved bonding strengths and coating thicknesses [6]. The binding mechanisms
295 discovered could not fully explain the high adhesion forces obtained. By using additional micro-
296 scopic analysis methods the remaining bonding mechanisms have been identified.

- 297 • Analysis of the joint zone shows no evidence of chemical reactions (inter-metallic com-
298 pounds) or diffusion.
- 299 • STEM and HRTEM analysis shows that the aluminium and the Al_2O_3 grains form a sharp
300 boundary without evidence of a reaction zone.
- 301 • Despite the use of high resolution TEM imaging at a sub nano-meter scale the separation
302 distance between the Al_2O_3 grains and the aluminium coating could not be identified, con-
303 cluding that the distance is lower than the scale factor of 1 nm.

304 It can be said that van der Waals forces are the main binding mechanisms for the $\text{Al}/\text{Al}_2\text{O}_3$
305 system, however the influence of mechanical interlocking on the van der Waals forces and its per-
306 sistence should not be trivialised.

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310 **6. Declaration of Conflicting Interests**

311 Mr. Atil reports grants from Dobeneck-Technologie-Stiftung during the conduct of the study.
312 The authors declare that they have no known competing financial interests or personal relationships
313 that could have appeared to influence the work reported in this paper.

314 **7. Data availability**

315 The raw/processed data required to reproduce these findings cannot be shared at this time as the
316 data also forms part of an ongoing study.

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